

# **MEDAN ELEKTROMAGNETIK RELATIVISTIK**

## **BINTANG NEUTRON STASIONER**

### **SKRIPSI**

Untuk memenuhi sebagian syarat memperoleh  
Derajat Sarjana S-1 Program Studi Fisika



Moh. Alifaki

07620008

**PROGRAM STUDI FISIKA  
FAKULTAS SAINS DAN TEKNOLOGI  
UIN SUNAN KALIJAGA  
YOGYAKARTA**

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**2015**



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Nomor : UIN.02/D.ST/PP.01.1/2409/2015

Skripsi/Tugas Akhir dengan judul : Medan Elektromagnetik Relativistik Bintang Neutron Stasioner

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*Assalamu'alaikum wr. wb.*

Setelah membaca, meneliti, memberikan petunjuk dan mengoreksi serta mengadakan perbaikan seperlunya, maka kami selaku pembimbing berpendapat bahwa skripsi Saudara:

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sudah dapat diajukan kembali kepada Program Studi Fisika Fakultas Sains dan Teknologi UIN Sunan Kalijaga Yogyakarta sebagai salah satu syarat untuk memperoleh gelar Sarjana Strata Satu dalam Program Studi Fisika

Dengan ini kami berharap agar skripsi/tugas akhir Saudara tersebut di atas dapat segera dimunaqsyahkan. Atas perhatiannya kami ucapkan terima kasih.

*Wassalamu'alaikum wr. wb.*

Yogyakarta, 8 Juli 2015

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*Embu' Maryati*  
*Ema' Rusipa*  
Almarhum *Eppa' Asyikurrahman*  
*Ale' Ahmad Sobiri Yanto*

## KATA PENGANTAR

Atas rampungnya skripsi berjudul “Medan Elektromagnetik Relativistik Bintang Neutron Stasioner” ini, penulis bersyukur ke hadirat Allah Subhanahu wa-Ta’ala dan semoga shalawat serta salam Allah tetap tercurahkan ke haribaan Nabi Muhammad Shallallahu ‘Alaihi wa-Sallam. Skripsi ini penulis persembahkan kepada ibu dan almarhum ayah tercinta – semoga Allah mengampuni dosa dan mengangkat derajat beliau berdua.

Hormat dan terima kasih penulis haturkan kepada Bapak Dr. rer. nat. Muhammad Farchani Rosyid dan Ibu Atsnaita Yasrina, M. Sc. yang senantiasa sabar dalam membimbing dan menyuntikkan semangat kepada penulis. Dan terima kasih pula saya ucapkan Bapak Joko Purwanto, M. Sc. yang sudi meluangkan waktu untuk menguji dan mengoreksi skripsi ini. Kepada para guru fisika penulis yang tidak bisa disebutkan satu-persatu, semoga ilmu yang penulis dapatkan dari beliau semua menjadi amal jariyah.

Terima kasih juga penulis ucapkan kepada keluarga besar penulis, dan kepada para guru serta teman-teman penulis di SDN 204 Kerta Timur Dasuk Sumenep, MTs 1 Annuqayah Guluk-Guluk Sumenep, SMA 1 Annuqayah Guluk-Guluk Sumenep, Pesantren At-Taqwa Kerta Timur Dasuk Sumenep (asuhan almarhum KH. Abd. Kahar), Pondok Pesantren Annuqayah Daerah Lubangsa Guluk-Guluk Sumenep (asuhan KH. A. Warits Ilyas), Pondok Pesantren Mahasiswa Hasyim Asy’arie Cabeyan Bantul (asuhan almarhum KH. Zainal Arifin Thoha), Pondok Pesantren Maulana Rumi Sewon Bantul (asuhan K. Kuswaidi Syafi’ie), dan Program Studi Fisika Fakultas Sains dan Teknologi Universitas Islam Negeri Sunan Kalijaga.

Secara khusus penulis juga mengucapkan terima kasih kepada Ibu Yuli Annisah, M. Si. yang telah memberikan banyak hal kepada penulis, termasuk laptop tempat skripsi ini dituliskan. Tidak lupa juga kepada beberapa pihak yang tidak bisa penulis sebutkan satu-persatu yang telah berdoa, menasehati dan menyemangati penulis di kala penulis merasa pesimis untuk lulus kuliah.

Yogyakarta, 03 Agustus 2015

Penulis

# **MEDAN ELEKTROMAGNETIK RELATIVISTIK BINTANG NEUTRON STASIONER**

Moh. Alifaki  
07620008

## **Intisari**

Telah dirumuskan persamaan medan elektromagnetik relativistik untuk bintang neutron stasioner dengan batasan konduktivitas di dalam bintang berhingga dan seragam serta medan magnet yang dikaji hanya medan magnet internal bintang. Hasilnya adalah tiga komponen persamaan medan elektromagnetik relativistik bintang neutron stasioner, yaitu komponen radial, komponen polar dan komponen toroidal.

*Kata-kata kunci: Bintang neutron, medan elektromagnetik relativistik.*



# **RELATIVISTIC ELECTROMAGNETIC FIELD OF THE STATIONARY NEUTRON STAR**

Moh. Alifaki  
07620008

## **Abstract**

Equation of relativistic electromagnetic field toward stationary neutron star has been formulated with constraint conductivity within finite and uniform star's interior and the studied magnetic field is only internal magnetic field of the star. The result which is identified for component equation of relativistic electromagnetic field in stationary neutron star has revealed three findings: radial component, polar component and toroidal component.

*Keywords: Neutron star, relativistic electromagnetic field.*

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# BAB I

## PENDAHULUAN

### 1.1. Latar Belakang Masalah

Bintang neutron merupakan kelompok bintang kompak di alam semesta. Kekompakan bintang neutron tersebut bisa dilihat dari besar massa dan rapat massanya. Jika dibandingkan dengan Matahari, masa bintang neutron adalah  $M \sim 1-2 M_{\odot}$  ( $M_{\odot} = 2 \times 10^{33}$  kg) dengan radius hanya  $R \approx 10-14$  km. Adapun rapat massanya tidaklah seragam. Di luar intinya, kerapatan bintang neutron tiga kali lebih rapat dibanding inti atom ( $\rho_0 = 2.8 \times 10^{14}$  g cm<sup>-3</sup>), yaitu  $\rho \sim 10^{15}$  g cm<sup>-3</sup>. Sedangkan rapat inti bintang neutron besarnya lebih dari  $\rho_0$  (Potekhin, 2011).

Oleh karena kekompakan bintang neutron itulah maka, untuk mengkajinya secara realistis, TRU (Teori Relativitas Umum) harus digunakan. Kekompakan sebuah objek relativistik ditentukan oleh parameter  $x_g = r_g/R$ , dengan  $r_g = 2GM/c^2 = 2.95 M/M_{\odot}$  disebut radius Schwarzschild (Potekhin, 2011). Misalnya untuk bintang neutron *kanonik* yang punya  $M = 1.4 M_{\odot}$  dan  $R = 12$  km, maka  $r_g = 4.13$  km dan  $x_g = 0.34$ . Hasil ini sesuai dengan kenyataan bahwa parameter kekompakan bintang secara umum  $x_g \ll 1$ . Artinya, jika  $x_g = 1$  adalah adalah 100%, maka nilai parameter 0.34 menunjukkan bintang neutron *kanonik* punya efek relativistik 10%.

Sementara itu, bintang neutron dikenal memiliki medan magnetik yang paling kuat di alam semesta (Potekhin, 2011). Besar medan magnet di permukaannya sekitar  $B \sim 10^8 - 10^{13}$  G, sedangkan di bagian dalamnya mencapai  $B \sim 10^{15}$  G (Bhattacharya, 2002). Umur medan magnet bintang neutron  $\pm 15 \times 10^9$  tahun, lebih lama dibanding umur alam semesta  $\pm 13 \times 10^9$  tahun (Potekhin, 2011). Namun anomali tersebut segera dapat teratasi, karena medan magnet bintang neutron menyusut secara dramatis, yaitu dari  $B \sim 10^{12}$  G menjadi  $B \sim 10^8$  G dalam skala waktu  $5 \times 10^6$  tahun (Zhang, 1997). Diduga bahwa penyusutan medan magnet ini disebabkan oleh tiga hal, yaitu ekspulsi spindown-induksi fluks, evolusi ohmik pada kerak dan peristiwa akresi

atau “memakannya” bintang neutron terhadap materi-materi di sekitar permukaannya atau terhadap bintang kawanannya untuk bintang neutron sistem ganda (Bhattacharya, 2002).

Secara logis, memang tidak mungkin elemen alam semesta seperti medan magnet bintang neutron berumur lebih lama dibanding alam semesta itu sendiri. Seluruh elemen alam semesta sudah ditetapkan ukurannya masing-masing oleh Allah Subhanahu Wa Ta’ala, dengan ukuran yang tidak mungkin menyalahi akal sehat manusia. Sebelum manusia menyadari hal tersebut, jauh-jauh hari Allah Subhanahu Wa Ta’ala sesungguhnya sudah mengisyaratkannya dalam al-Qur’an surah al-Qomar [54] ayat 49 (Depag RI, 2007):

*“Sesungguhnya Kami menciptakan segala sesuatu dengan ukuran”.*

Dan di dalam al-Qur’an surah al-Jaatsiyah [45] ayat 13 (Depag RI, 2007), Allah Subhanahu Wa Ta’ala berfirman:

*“Dan Dia menundukkan untukmu apa yang ada di langit dan apa yang ada di bumi semuanya (sebagai rahmat) daripadaNya. Sesungguhnya pada yang demikian itu benar-benar terdapat tanda-tanda (kekuasaan Allah) bagi kaum yang berpikir”.*

Dalam (QS 54: 49), Allah Subhanahu Wa Ta’ala menegaskan bahwa tidak ada satu pun elemen alam semesta yang tidak terukur. Hanya saja Allah Subhanahu Wa Ta’ala membebaskan kepada manusia berpikir tentang “alat ukur” macam apa yang dapat dipakai untuk mengukur ukuran elemen alam semesta yang telah ditetapkan oleh Allah Subhanahu Wa Ta’ala tersebut. Alat ukur yang manusia pakai untuk mengukur elemen alam semesta, dalam konteks ini bintang neutron, adalah teori-teori fisika yang sudah difalsafikasi (sudah memenuhi standar-standar logis konvensional).

Sementara kata “*Dia (Allah) menundukkan*” dalam (QS 45: 13) berarti bahwa alat ukur yang dipakai manusia, sepanjang memenuhi terma-terma logis, “ukuran”

alam semesta tidak akan pernah bertentangan dengan akal sehat manusia, karena dengan kasih-sayangNya, pada mulanya Allah Subhanahu Wa Ta'ala telah “menundukkan” alam semesta ini kepada manusia. Kalau manusia tidak mampu memahami anomali dari “ukuran” alam semesta bukan berarti Allah Subhanahu Wa Ta'ala menyembunyikannya (tidak “menundukkan”), tetapi pasti alat ukur yang digunakan oleh manusia tersebut bermasalah.

Sekarang sudah ditemukan sumber pemecah anomali dari umur medan magnet bintang neutron tersebut, yakni bahwa medan magnet bintang neutron menyusut. Dengan adanya gejala penyusutan medan magnet bintang neutron yang ditengarai dikarenakan peristiwa akresi bintang neutron terhadap bintang kawanannya menjadi alasan logis tentang bahwa umur medan magnet bintang neutron tidak mungkin melebihi umur alam semesta. Di sini berarti alat ukur fisis yang digunakan untuk menelaah medan magnet bintang neutron sudah benar, karena dengan alat ukur tersebut fenomena medan magnet bintang neutron menjadi logis.

Berangkat dari kenyataan tersebut, cara untuk mengetahui penyusutan medan magnet bintang neutron, diperlukan persamaan dinamika medan magnet pada bintang neutron itu sendiri. Dalam rangka memperoleh persamaan dinamika medan magnetik bintang neutron, para peneliti sebelumnya menggunakan beberapa model dan batasan. Ada yang membatasi medan magnetik bintang neutron dalam dua dimensi (bintang dianggap flat), ada yang membatasi untuk bintang neutron non-relativistik stasioner, ada yang membatasi untuk bintang neutron relativistik berotasi lambat, dan ada juga yang membatasi untuk bintang neutron non-relativistik berotasi cepat.

Di dalam penelitian ini, akan dikaji dinamika medan magnetik (yang digambarkan oleh persamaan Maxwell) bintang neutron yang stasioner dalam kerangka TRU. Ini dimaksudkan untuk memperoleh gambaran tentang bagaimanakah dinamika medan elektromagnetik pada bintang neutron stasioner. Hasilnya diharapkan dapat membantu untuk merumuskan persamaan penyusutan medan elektromagnetik relativistik bintang neutron stasioner pada penelitian-penelitian berikutnya di masa mendatang.

Tidak hanya itu, hasil rumusan yang diperoleh dalam penelitian ini nantinya diharapkan dapat dipergunakan sebagai bahan kajian pengembangan perumusan dinamika medan elektromagnetik relativistik pada bintang neutron non-stasioner, baik berotasi lambat maupun berotasi cepat. Kajian tersebut diharapkan mengandaikan bagian luar bintang terdapat materi sedemikian sehingga memungkinkan adanya proses akresi. Hal ini dibutuhkan karena peristiwa akresi diduga menjadi penyebab utama menyusutnya medan magnet di bintang neutron.

## **1.2. Rumusan Masalah**

Berdasarkan uraian latar belakang masalah di atas, maka permasalahan yang akan diteliti dalam penelitian ini dirumuskan sebagai berikut:

Bagaimana rumusan persamaan dinamika medan magnet relativistik bintang neutron stasioner?

## **1.3. Tujuan Penelitian**

Berdasarkan rumusan masalah tersebut, maka penelitian ini memiliki tujuan, yaitu untuk merumuskan persamaan dinamika medan elektromagnetik relativistik bintang neutron stasioner.

## **1.4. Batasan Penelitian**

Untuk mencapai tujuan yang diinginkan, maka batasan penelitian ini ditentukan sebagai berikut:

1. Konduktivitas listriknya berhingga dan di dalam bintang bernilai seragam.
2. Medan magnet yang dikaji hanyalah medan magnet internal bintang neutron.
3. Bintang neutron dalam keadaan stasioner.
4. Bintang neutron tidak mengakresi.

### **1.5. Manfaat Penelitian**

Setelah penelitian ini sudah dilakukan, maka hasil yang diperoleh diharapkan dapat memberikan manfaat, antara lain:

1. Memberikan pemahaman yang lebih luas khususnya kepada peneliti sendiri tentang teori medan elektromagnetik relativistik dalam penerapannya terhadap bintang neutron stasioner.
2. Dapat dipergunakan sebagai pedoman untuk memformulasikan persamaan penyusutan medan magnet bintang neutron yang selama ini menjadi isu krusial dalam astrofisika.
3. Dapat dipergunakan sebagai bahan kajian pengembangan perumusan dinamika medan elektromagnetik bintang neutron relativistik non-stasioner, baik yang berotasi lambat maupun berotasi cepat, serta menyusutnya medan magnet bintang neutron yang diduga diakibatkan oleh aktivitas akresi bintang.



## **BAB V**

### **KESIMPULAN DAN SARAN**

#### **5.1. Kesimpulan**

Berdasarkan pada tujuan penelitian ini, maka rumusan dinamika medan elektromagnetik relativistik bintang neutron stasioner disajikan oleh persamaan (4.94) untuk komponen radial, persamaan (4.95) untuk komponen polar, dan persamaan (4.96) untuk komponen toroidal. Penelitian ini hanya menghasilkan persamaan dinamika medan elektromagnetik pada bintang neutron stasioner. Oleh karenanya persamaan ini tidak dapat digunakan untuk menghitung penyusutan medan magnet bintang neutron. Akan tetapi persamaan ini sangat penting, karena persamaan ini dapat membantu para peneliti lain di masa mendatang untuk memformulasikan persamaan penyusutan medan magnet pada bintang neutron yang selama ini menjadi isu krusial dalam astrofisika.

#### **5.2. Saran**

Kajian penelitian ini masih dibatasi pada tiga ruang lingkup, yaitu medan magnet internal bintang neutron, konduktivitas listrik di dalam bintang bernilai seragam, dan bintang neutron dianggap stasioner. Oleh karena itu, maka peneliti merekomendasikan beberapa saran untuk penelitian-penelitian berikutnya, yaitu:

1. Merumuskan persamaan penyusutan medan magnet bintang neutron stasioner berdasarkan pada hasil persamaan dinamika medan elektromagnetik relativistik bintang neutron stasioner di penelitian ini.
2. Merumuskan persamaan dinamika medan elektromagnetik relativistik pada bintang neutron stasioner dengan menganggap konduktivitas listriknya di dalam bintang tidak seragam.
3. Merumuskan persamaan dinamika medan elektromagnetik relativistik pada bintang neutron stasioner dengan menggunakan ruang-waktu eksternal bintang.

4. Merumuskan persamaan dinamika medan elektromagnetik relativistik pada bintang neutron stasioner bila dianggap ada perpindahan arus dari luar bintang ke dalam bintang.
5. Merumuskan persamaan dinamika medan elektromagnetik relativistik pada bintang neutron non-stasioner, baik berotasi lambat maupun berotasi cepat, baik adanya perpindahan arus atau tidak.
6. Merumuskan persamaan dinamika medan elektromagnetik baik pada bintang neutron stasioner maupun non-stasioner menggunakan ruang-waktu bermetrik elipsoid, mengingat pada kenyataannya kontur bintang bukanlah simetri bola, akan tetapi elipsoidal.

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Neutron yang Berotasi Lambat (Tesis)*. Yogyakarta: Jurusan Fisika FMIPA  
UGM.

**LAMPIRAN A**  
**PENURUNAN PERSAMAAN MAXWELL I**

Geometri bintang neutron stasioner diberikan oleh

$$ds^2 = -e^{2\phi(r)} dt^2 + e^{2\Lambda(r)} dr^2 + r^2 d\theta^2 + r^2 \sin^2 \theta d\varphi^2 \quad (\text{A.1})$$

dengan

$$g_{\alpha\beta} = \begin{bmatrix} g_{00} & g_{01} & g_{02} & g_{03} \\ g_{10} & g_{11} & g_{12} & g_{13} \\ g_{20} & g_{21} & g_{22} & g_{23} \\ g_{30} & g_{31} & g_{32} & g_{33} \end{bmatrix} = \begin{bmatrix} -e^{2\phi(r)} & 0 & 0 & 0 \\ 0 & e^{2\Lambda(r)} & 0 & 0 \\ 0 & 0 & r^2 & 0 \\ 0 & 0 & 0 & r^2 \sin^2 \theta \end{bmatrix} \quad (\text{A.2})$$

dan nilai tiap komponen tak-nolnya

$$\begin{aligned} g_{00} &= -e^{2\phi(r)} \\ g_{11} &= e^{2\Lambda(r)} \\ g_{22} &= r^2 \\ g_{33} &= r^2 \sin^2 \theta. \end{aligned} \quad (\text{A.3})$$

Dengan demikian, metrik skalarnya

$$\begin{aligned}
g = \det |g_{\alpha\beta}| &= -e^{2\phi(r)} \begin{bmatrix} e^{2\Lambda(r)} & 0 & 0 \\ 0 & r^2 & 0 \\ 0 & 0 & r^2 \sin^2 \theta \end{bmatrix} = -e^{2\phi(r)} \{e^{2\Lambda(r)} r^4 \sin^2 \theta\} \\
&= -e^{2[\phi+\Lambda](r)} r^4 \sin^2 \theta
\end{aligned} \tag{A.4}$$

dan

$$\sqrt{-g} = \sqrt{e^{2(\phi+\Lambda)(r)} r^4 \sin^2 \theta} = e^{[\phi+\Lambda](r)} r^2 \sin \theta \tag{A.5}$$

Dari kenyataan bahwa

$$ds^2 = -c^2 dt^2 + dx^2 + dy^2 + dz^2$$

maka diketahui kecepatan medan kovarian dan kontravarian

$$\begin{aligned}
u_0 &= e^{\phi(r)} (-1, 0, 0, 0) \\
u^0 &= e^{-\phi(r)} (1, 0, 0, 0).
\end{aligned} \tag{A.6}$$

Sementara itu, Persamaan Maxwell I seperti ditunjukkan oleh persamaan (2.131). Dari persamaan tersebut, dibutuhkan perhitungan tensor kuat-medan elektromagnetik yang persamaannya diberikan oleh (2.141)

$$\begin{aligned}
F_{\alpha\beta} &= 2u_{[\alpha} E_{\beta]} + \eta_{\alpha\beta\gamma\delta} u^\gamma B^\delta = u_\alpha E_\beta - u_\beta E_\alpha + \sqrt{-g} \epsilon_{\alpha\beta\gamma\delta} u^\gamma B^\delta \\
F_{\beta\alpha} &= 2u_{[\beta} E_{\alpha]} + \eta_{\beta\alpha\gamma\delta} u^\gamma B^\delta = u_\beta E_\alpha - u_\alpha E_\beta + \sqrt{-g} \epsilon_{\beta\alpha\gamma\delta} u^\gamma B^\delta \\
&= -(u_\alpha E_\beta - u_\beta E_\alpha + \sqrt{-g} \epsilon_{\alpha\beta\gamma\delta} u^\gamma B^\delta) = -F_{\alpha\beta}
\end{aligned} \tag{A.7}$$

bersifat anti-simetrik. Berikut komponen-komponennya:

3. Untuk  $\alpha = \beta$

$$F_{\alpha\alpha} = u_\alpha E_\alpha - u_\alpha E_\alpha + \sqrt{-g} \epsilon_{\alpha\alpha\gamma\delta} u^\gamma B^\delta = \sqrt{-g} \epsilon_{\alpha\alpha\gamma\delta} u^\gamma B^\delta.$$

Karena simbol Levi-Civita untuk  $\epsilon_{\alpha\alpha\gamma\delta} = 0$ , maka

$$F_{00} = F_{11} = F_{22} = F_{33} = 0$$

(A.8)

4. Untuk  $\alpha \neq \beta$

$$F_{\alpha\beta} = 2u_{[\alpha} E_{\beta]} + \eta_{\alpha\beta\gamma\delta} u^\gamma B^\delta = u_\alpha E_\beta - u_\beta E_\alpha + \sqrt{-g} \epsilon_{\alpha\beta\gamma\delta} u^\gamma B^\delta$$

- Untuk  $\alpha = 0$  dan  $\beta = 1$

$$F_{01} = u_0 E_1 - u_1 E_0 + \sqrt{-g} (\epsilon_{0123} u^2 B^3 - \epsilon_{0132} u^3 B^2)$$

Karena  $u_1 = 0$ ,  $u^2 = 0$  dan  $u^3 = 0$ , maka

$$F_{01} = u_0 E_1 = -e^{\phi(r)} E_r = -F_{10}$$

(A.9)

- Untuk  $\alpha = 0$  dan  $\beta = 2$

$$F_{02} = u_0 E_2 - u_2 E_0 + \sqrt{-g}(\epsilon_{0231} u^3 B^1 - \epsilon_{0213} u^1 B^3)$$

$$F_{02} = u_0 E_2 = -e^{\phi(r)} E_\theta = -F_{20}$$

(A.10)

- Untuk  $\alpha = 0$  dan  $\beta = 3$

$$F_{03} = u_0 E_3 - u_3 E_0 + \sqrt{-g}(\epsilon_{0312} u^1 B^2 - \epsilon_{0321} u^2 B^1)$$

$$F_{03} = u_0 E_3 = -e^{\phi(r)} E_\varphi = -F_{30}$$

(A.11)

- Untuk  $\alpha = 1$  dan  $\beta = 2$

$$F_{12} = u_1 E_2 - u_2 E_1 + \sqrt{-g}(\epsilon_{1230} u^3 B^0 - \epsilon_{1203} u^0 B^3)$$

$$F_{12} = \sqrt{-g}(\epsilon_{1203} u^0 B^3)$$

Dengan permutasi simbol Levi-Civita  $\epsilon_{1203} = -\epsilon_{0213} = -(-\epsilon_{0123}) = +1$ , maka

$$F_{12} = e^{[\phi+\Lambda](r)} r^2 \sin \theta e^{-\phi(r)} B^\varphi = e^{\Lambda(r)} r^2 \sin \theta B^\varphi = -F_{21}$$

(A.12)

- Untuk  $\alpha = 1$  dan  $\beta = 3$

$$F_{13} = u_1 E_3 - u_3 E_1 + \sqrt{-g}(\epsilon_{1302} u^0 B^2 - \epsilon_{1320} u^2 B^0)$$



$$F_{13} = \sqrt{-g}(\epsilon_{1302}u^0B^2)$$

Dengan permutasi simbol Levi-Civita  $\epsilon_{1302} = -\epsilon_{0312} = -(-\epsilon_{0132}) = -\epsilon_{0123} = -1$ , maka

$$F_{13} = -e^{[\phi+\Lambda](r)}r^2\sin\theta e^{-\phi(r)}B^\theta = -e^{\Lambda(r)}r^2\sin\theta B^\theta = -F_{31} \quad (\text{A.13})$$

- Untuk  $\alpha = 2$  dan  $\beta = 3$

$$F_{23} = u_2E_3 - u_3E_2 + \sqrt{-g}(\epsilon_{2301}u^0B^1 - \epsilon_{2310}u^1B^0)$$

$$F_{23} = \sqrt{-g}(\epsilon_{2301}u^0B^2)$$

Dengan permutasi simbol Levi-Civita  $\epsilon_{2301} = -\epsilon_{0321} = -(-\epsilon_{0123}) = +1$ , maka

$$F_{23} = e^{[\phi+\Lambda](r)}r^2\sin\theta e^{-\phi(r)}B^r = e^{\Lambda(r)}r^2\sin\theta B^r = -F_{32} \quad (\text{A.14})$$

Jadi, tensor kuat-medan elektromagnetik kovarian diberikan oleh

$$F_{\alpha\beta} = \begin{bmatrix} 0 & -e^{\phi(r)}E_r & -e^{\phi(r)}E_\theta & -e^{\phi(r)}E_\varphi \\ e^{\phi(r)}E_r & 0 & e^{\Lambda(r)}r^2\sin\theta B^\varphi & -e^{\Lambda(r)}r^2\sin\theta B^\theta \\ e^{\phi(r)}E_\theta & -e^{\Lambda(r)}r^2\sin\theta B^\varphi & 0 & e^{\Lambda(r)}r^2\sin\theta B^r \\ e^{\phi(r)}E_\varphi & e^{\Lambda(r)}r^2\sin\theta B^\theta & -e^{\Lambda(r)}r^2\sin\theta B^r & 0 \end{bmatrix} \quad (\text{A.15})$$

Turunan parsial tensor kuat-medan elektromagnetik adalah

5. Untuk  $\alpha = \alpha = \alpha$

Karena  $F_{\alpha\alpha\alpha} = 0$ , maka

$$F_{00,0} = F_{11,1} = F_{22,2} = F_{33,3} = 0 \quad (\text{A.16})$$

6. Untuk  $\alpha = \beta \neq \gamma$

Karena  $F_{\alpha\alpha} = 0$  yang mengimplikasikan  $F_{\alpha\alpha,\gamma} = 0$ , maka

$$\begin{aligned} F_{00,1} = F_{00,2} = F_{00,3} &= 0 \\ F_{11,0} = F_{11,2} = F_{11,3} &= 0 \\ F_{22,0} = F_{22,1} = F_{00,3} &= 0 \\ F_{33,0} = F_{33,1} = F_{33,2} &= 0 \end{aligned} \quad (\text{A.17})$$

7. Untuk  $\alpha = \gamma \neq \beta$

- Untuk  $\alpha = \gamma = 0$

Dengan  $\beta = 1$

$$F_{01,0} = \frac{\partial(F_{01})}{\partial t} = \frac{\partial(-e^{\phi(r)}E_r)}{\partial t} = -\frac{\partial e^{\phi(r)}}{\partial t}E_r - \frac{\partial E_r}{\partial t}e^{\phi(r)} = -\frac{\partial E_r}{\partial t}e^{\phi(r)} = -F_{10,0} \quad (\text{A.18})$$

Dengan  $\beta = 2$

$$F_{02,0} = \frac{\partial(F_{02})}{\partial t} = \frac{\partial(-e^{\phi(r)}E_{\theta})}{\partial t} = -\frac{\partial e^{\phi(r)}}{\partial t}E_{\theta} - \frac{\partial E_{\theta}}{\partial t}e^{\phi(r)} = -\frac{\partial E_{\theta}}{\partial t}e^{\phi(r)} = -F_{20,0}$$

(A.19)

Dengan  $\beta = 3$

$$F_{03,0} = \frac{\partial(F_{03})}{\partial t} = \frac{\partial(-e^{\phi(r)}E_{\varphi})}{\partial t} = -\frac{\partial e^{\phi(r)}}{\partial t}E_{\varphi} - \frac{\partial E_{\varphi}}{\partial t}e^{\phi(r)} = -\frac{\partial E_{\varphi}}{\partial t}e^{\phi(r)} = -F_{30,0}$$

(A.20)

- Untuk  $\alpha = \gamma = 1$

Dengan  $\beta = 0$

$$F_{10,1} = \frac{\partial(F_{10})}{\partial r} = \frac{\partial(e^{\phi(r)}E_r)}{\partial r} = (e^{\phi(r)}E_r)_{,r} = -F_{01,1}$$

(A.21)

Dengan  $\beta = 2$

$$F_{12,1} = \frac{\partial(F_{12})}{\partial r} = \frac{\partial(e^{\Lambda(r)}r^2 \sin \theta B^{\varphi})}{\partial r} = \sin \theta (e^{\Lambda(r)}r^2 B^{\varphi})_{,r} = -F_{21,1}$$

(A.22)

Dengan  $\beta = 3$

$$F_{13,1} = \frac{\partial(F_{13})}{\partial r} = \frac{\partial(-e^{\Lambda(r)}r^2 \sin \theta B^{\theta})}{\partial r} = -\sin \theta (e^{\Lambda(r)}r^2 B^{\theta})_{,r} = -F_{31,1}$$

(A.23)

- Untuk  $\alpha = \gamma = 2$

Dengan  $\beta = 0$

$$F_{20,2} = \frac{\partial(F_{20})}{\partial\theta} = \frac{\partial(e^{\phi(r)}E_\theta)}{\partial\theta} = e^{\phi(r)}(E_\theta)_{,\theta} = -F_{02,2} \quad (\text{A.24})$$

Dengan  $\beta = 1$

$$F_{21,2} = \frac{\partial(F_{21})}{\partial\theta} = \frac{\partial(-e^{\Lambda(r)}r^2\sin\theta B^\varphi)}{\partial\theta} = -e^{\Lambda(r)}r^2(\sin\theta B^\varphi)_{,\theta} = -F_{12,2} \quad (\text{A.25})$$

Dengan  $\beta = 3$

$$F_{23,2} = \frac{\partial(F_{23})}{\partial\theta} = \frac{\partial(e^{\Lambda(r)}r^2\sin\theta B^r)}{\partial\theta} = e^{\Lambda(r)}r^2(\sin\theta B^r)_{,\theta} = -F_{32,3} \quad (\text{A.26})$$

- Untuk  $\alpha = \gamma = 3$

Dengan  $\beta = 0$

$$F_{30,3} = \frac{\partial(F_{30})}{\partial\varphi} = \frac{\partial(e^{\phi(r)}E_\varphi)}{\partial\varphi} = e^{\phi(r)}(E_\varphi)_{,\varphi} = -F_{03,3} \quad (\text{A.27})$$

Dengan  $\beta = 1$

$$F_{31,3} = \frac{\partial(F_{31})}{\partial\varphi} = \frac{\partial(e^{\Lambda(r)}r^2\sin\theta B^\theta)}{\partial\varphi} = e^{\phi(r)}r^2\sin\theta (B^\theta)_{,\varphi} = -F_{13,3}$$

(A.28)

Dengan  $\beta = 2$

$$F_{32,3} = \frac{\partial(F_{32})}{\partial\varphi} = \frac{\partial(-e^{\Lambda(r)}r^2\sin\theta B^r)}{\partial\varphi} = -e^{\phi(r)}r^2\sin\theta (B^r)_{,\varphi} = -F_{23,3}$$

(A.29)

8. Untuk  $\alpha \neq \gamma \neq \beta$

$\alpha = 0$  dan  $\beta = 1$

- Dengan  $\gamma = 2$

$$F_{01,2} = \frac{\partial(F_{01})}{\partial\theta} = \frac{\partial(-e^{\phi(r)}E_r)}{\partial\theta} = -e^{\phi(r)}(E_r)_{,\theta} = -F_{10,2}$$

(A.30)

- Dengan  $\gamma = 3$

$$F_{01,3} = \frac{\partial(F_{01})}{\partial\varphi} = \frac{\partial(-e^{\phi(r)}E_r)}{\partial\varphi} = -e^{\phi(r)}(E_r)_{,\varphi} = -F_{10,3}$$

(A.31)

$\alpha = 0$  dan  $\beta = 2$

- Dengan  $\gamma = 1$

$$F_{02,1} = \frac{\partial(F_{02})}{\partial r} = \frac{\partial(-e^{\phi(r)}E_\theta)}{\partial r} = -(e^{\phi(r)}E_\theta)_{,r} = -F_{20,1}$$

(A.32)

- Dengan  $\gamma = 3$

$$F_{02,3} = \frac{\partial(F_{02})}{\partial\varphi} = \frac{\partial(-e^{\phi(r)}E_{\theta})}{\partial\varphi} = -e^{\phi(r)}(E_{\theta})_{,\varphi} = -F_{20,3}$$
(A.33)

 $\alpha = 0$  dan  $\beta = 3$ 

- Dengan  $\gamma = 1$

$$F_{03,1} = \frac{\partial(F_{03})}{\partial r} = \frac{\partial(-e^{\phi(r)}E_{\varphi})}{\partial r} = -(e^{\phi(r)}E_{\varphi})_{,r} = -F_{30,1}$$
(A.34)

- Dengan  $\gamma = 2$

$$F_{03,2} = \frac{\partial(F_{03})}{\partial\theta} = \frac{\partial(-e^{\phi(r)}E_{\varphi})}{\partial\theta} = -e^{\phi(r)}(E_{\varphi})_{,\theta} = -F_{30,2}$$
(A.35)

 $\alpha = 1$  dan  $\beta = 2$ 

- Dengan  $\gamma = 0$

$$F_{12,0} = \frac{\partial(F_{12})}{\partial t} = \frac{\partial(e^{\Lambda(r)}r^2\sin\theta B^{\varphi})}{\partial t} = e^{\Lambda(r)}r^2\sin\theta (B^{\varphi})_{,t} = -F_{21,0}$$
(A.36)

- Dengan  $\gamma = 3$

$$F_{12,3} = \frac{\partial(F_{12})}{\partial\varphi} = \frac{\partial(e^{\Lambda(r)}r^2\sin\theta B^\varphi)}{\partial\varphi} = e^{\Lambda(r)}r^2\sin\theta (B^\varphi)_{,\varphi} = -F_{21,3} \quad (\text{A.37})$$

$\alpha = 1$  dan  $\beta = 3$

- Dengan  $\gamma = 0$

$$F_{13,0} = \frac{\partial(F_{13})}{\partial t} = \frac{\partial(-e^{\Lambda(r)}r^2\sin\theta B^\theta)}{\partial t} = -e^{\Lambda(r)}r^2\sin\theta (B^\theta)_{,t} = -F_{31,0} \quad (\text{A.38})$$

- Dengan  $\gamma = 2$

$$F_{13,2} = \frac{\partial(F_{13})}{\partial\theta} = \frac{\partial(-e^{\Lambda(r)}r^2\sin\theta B^\theta)}{\partial\theta} = -e^{\Lambda(r)}r^2(\sin\theta B^\theta)_{,\theta} = -F_{31,2} \quad (\text{A.39})$$

$\alpha = 2$  dan  $\beta = 3$

- Dengan  $\gamma = 0$

$$F_{23,0} = \frac{\partial(F_{23})}{\partial t} = \frac{\partial(e^{\Lambda(r)}r^2\sin\theta B^r)}{\partial t} = e^{\Lambda(r)}r^2\sin\theta (B^r)_{,t} = -F_{32,0} \quad (\text{A.40})$$

- Dengan  $\gamma = 1$

$$F_{23,1} = \frac{\partial(F_{23})}{\partial r} = \frac{\partial(e^{\Lambda(r)}r^2\sin\theta B^r)}{\partial r} = \sin\theta (e^{\Lambda(r)}r^2 B^r)_{,r} = -F_{32,1}$$

(A.41)

Persamaan Maxwell I tidak lenyap jika  $\alpha \neq \gamma \neq \beta$ . Maka komponen-komponennya dapat dituliskan sebagai berikut

- Untuk permutasi 012

$$\begin{aligned}
 F_{01,2} + F_{20,1} + F_{12,0} &= 0 \\
 -e^{\phi(r)}(E_r)_{,\theta} + (e^{\phi(r)}E_\theta)_{,r} + e^{\Lambda(r)}r^2 \sin \theta (B^\varphi)_{,t} &= 0 \\
 e^{\Lambda(r)}r^2 \sin \theta \frac{\partial B^\varphi}{\partial t} &= (e^{\phi(r)}E_\theta)_{,r} - e^{\phi(r)}(E_r)_{,\theta}
 \end{aligned}
 \tag{A.42}$$

- Untuk permutasi 013

$$\begin{aligned}
 F_{01,3} + F_{30,1} + F_{13,0} &= 0 \\
 -e^{\phi(r)}(E_r)_{,\varphi} + (e^{\phi(r)}E_\varphi)_{,r} e^{\Lambda(r)}r^2 \sin \theta (B^\theta)_{,t} &= 0 \\
 e^{\Lambda(r)}r^2 \sin \theta \frac{\partial B^\theta}{\partial t} &= (e^{\phi(r)}E_\varphi)_{,r} - e^{\phi(r)}(E_r)_{,\varphi}
 \end{aligned}
 \tag{A.43}$$

- Untuk permutasi 023

$$\begin{aligned}
 F_{02,3} + F_{30,2} + F_{23,0} &= 0 \\
 -e^{\phi(r)}(E_\theta)_{,\varphi} + e^{\phi(r)}(E_\varphi)_{,\theta} + e^{\Lambda(r)}r^2 \sin \theta (B^r)_{,t} &= 0 \\
 e^{\Lambda(r)}r^2 \sin \theta \frac{\partial B^r}{\partial t} &= e^{\phi(r)}(E_\varphi)_{,\theta} - e^{\phi(r)}(E_\theta)_{,\varphi}
 \end{aligned}
 \tag{A.44}$$



- Untuk permutasi 123

$$\begin{aligned}
 & F_{12,3} + F_{31,2} + F_{23,1} = 0 \\
 & e^{\Lambda(r)} r^2 \sin \theta (B^\varphi)_{,\varphi} + e^{\Lambda(r)} r^2 (\sin \theta B^\theta)_{,\theta} + \sin \theta (e^{\Lambda(r)} r^2 B^r)_{,r} = 0
 \end{aligned}
 \tag{A.45}$$

**LAMPIRAN B**  
**PENURUNAN PERSAMAAN MAXWELL II**

Tensor kuat-medan elektromagnetik diberikan oleh (A.15) di mana determinannya

$$\det |F_{\alpha\beta}| = 0 + e^{\phi(r)} E_r \begin{bmatrix} e^{\phi(r)} E_r & e^{\Lambda(r)} r^2 \sin \theta B^\varphi & -e^{\Lambda(r)} r^2 \sin \theta B^\theta \\ e^{\phi(r)} E_\theta & 0 & e^{\Lambda(r)} r^2 \sin \theta B^r \\ e^{\phi(r)} E_\varphi & -e^{\Lambda(r)} r^2 \sin \theta B^r & 0 \end{bmatrix}$$

$$- e^{\phi(r)} E_\theta \begin{bmatrix} e^{\phi(r)} E_r & 0 & -e^{\Lambda(r)} r^2 \sin \theta B^\theta \\ e^{\phi(r)} E_\theta & -e^{\Lambda(r)} r^2 \sin \theta B^\varphi & e^{\Lambda(r)} r^2 \sin \theta B^r \\ e^{\phi(r)} E_\varphi & e^{\Lambda(r)} r^2 \sin \theta B^\theta & 0 \end{bmatrix}$$

$$+ e^{\phi(r)} E_\varphi \begin{bmatrix} e^{\phi(r)} E_r & 0 & e^{\Lambda(r)} r^2 \sin \theta B^\varphi \\ e^{\phi(r)} E_\theta & -e^{\Lambda(r)} r^2 \sin \theta B^\varphi & 0 \\ e^{\phi(r)} E_\varphi & e^{\Lambda(r)} r^2 \sin \theta B^\theta & -e^{\Lambda(r)} r^2 \sin \theta B^r \end{bmatrix}$$

$$\det |F_{\alpha\beta}| = e^{\phi(r)} E_r \{ e^{\phi(r)} E_r [0 + e^{2\Lambda(r)} (r^2 \sin \theta B^r)^2]$$

$$- e^{\Lambda(r)} r^2 \sin \theta B^\varphi [0$$

$$- e^{[\phi+\Lambda](r)} r^2 \sin \theta B^r E_\varphi] - e^{\Lambda(r)} r^2 \sin \theta B^\theta [-e^{[\phi+\Lambda](r)} r^2 \sin \theta B^r E_\theta$$

$$- 0] \}$$

$$- e^{\phi(r)} E_\theta \{ e^{\phi(r)} E_r [0 - e^{2\Lambda(r)} (r^2 \sin \theta)^2 B^r B^\theta]$$

$$- 0 - e^{\Lambda(r)} r^2 \sin \theta B^\theta [e^{[\phi+\Lambda](r)} r^2 \sin \theta B^\theta E_\theta$$

$$+ e^{[\phi+\Lambda](r)} r^2 \sin \theta B^\varphi E_\varphi] \}$$

$$+ e^{\phi(r)} E_\varphi \{ e^{\phi(r)} E_r [e^{2\Lambda(r)} (r^2 \sin \theta)^2 B^\varphi B^r - 0] - 0$$

$$+ e^{\Lambda(r)} r^2 \sin \theta B^\varphi [e^{[\phi+\Lambda](r)} r^2 \sin \theta B^\theta E_\theta$$

$$+ e^{[\phi+\Lambda](r)} r^2 \sin \theta B^\varphi E_\varphi] \}$$

$$\begin{aligned}
\det |F_{\alpha\beta}| &= e^{\phi(r)} E_r \{ e^{[\phi+2\Lambda](r)} (r^2 \sin \theta B^r)^2 E_r + e^{[\phi+2\Lambda](r)} (r^2 \sin \theta)^2 B^\varphi B^r E_\varphi \\
&\quad - e^{[\phi+2\Lambda](r)} (r^2 \sin \theta)^2 B^\theta B^r E_\theta \} \\
&\quad - e^{\phi(r)} E_\theta \{ -e^{[\phi+2\Lambda](r)} (r^2 \sin \theta)^2 B^r B^\theta E_r - e^{[\phi+2\Lambda](r)} (r^2 \sin \theta)^2 B^\theta B^\theta E_\theta \\
&\quad - e^{[\phi+2\Lambda](r)} (r^2 \sin \theta)^2 B^\theta B^\varphi E_\varphi \} \\
&\quad + e^{\phi(r)} E_\varphi \{ e^{[\phi+2\Lambda](r)} (r^2 \sin \theta)^2 E_r B^\varphi B^r + e^{[\phi+2\Lambda](r)} (r^2 \sin \theta)^2 B^\varphi B^\theta E_\theta \\
&\quad + e^{[\phi+2\Lambda](r)} (r^2 \sin \theta)^2 B^\varphi B^\varphi E_\varphi \}
\end{aligned}$$

$$\begin{aligned}
\det |F_{\alpha\beta}| &= \{ e^{2[\phi+\Lambda](r)} (r^2 \sin \theta)^2 B^r B^r E_r E_r + e^{2[\phi+\Lambda](r)} (r^2 \sin \theta)^2 B^\varphi B^r E_\varphi E_r \\
&\quad + e^{2[\phi+\Lambda](r)} (r^2 \sin \theta)^2 B^\theta B^r E_\theta E_r \} \\
&\quad + \{ e^{2[\phi+\Lambda](r)} (r^2 \sin \theta)^2 B^r B^\theta E_r E_\theta + e^{2[\phi+\Lambda](r)} (r^2 \sin \theta)^2 B^\theta B^\theta E_\theta E_\theta \\
&\quad + e^{2[\phi+\Lambda](r)} (r^2 \sin \theta)^2 B^\theta B^\varphi E_\theta E_\varphi \} \\
&\quad + \{ e^{2[\phi+\Lambda](r)} (r^2 \sin \theta)^2 B^\varphi B^r E_\varphi E_r + e^{2[\phi+\Lambda](r)} (r^2 \sin \theta)^2 B^\varphi B^\theta E_\varphi E_\theta \\
&\quad + e^{2[\phi+\Lambda](r)} (r^2 \sin \theta)^2 B^\varphi B^\varphi E_\varphi E_\varphi \}
\end{aligned}$$

$$\begin{aligned}
\det |F_{\alpha\beta}| &= e^{2[\phi+\Lambda](r)} (r^2 \sin \theta E_r)^2 + e^{2[\phi+\Lambda](r)} (r^2 \sin \theta B^\theta E_\theta)^2 \\
&\quad + e^{2[\phi+\Lambda](r)} (r^2 \sin \theta B^\varphi E_\varphi)^2 + 2e^{2[\phi+\Lambda](r)} (r^2 \sin \theta)^2 B^\varphi B^r E_\varphi E_r \\
&\quad + 2e^{2[\phi+\Lambda](r)} (r^2 \sin \theta)^2 B^\varphi B^\theta E_\varphi E_\theta \\
&\quad + 2e^{2[\phi+\Lambda](r)} (r^2 \sin \theta)^2 B^r B^\theta E_r E_\theta
\end{aligned}$$

$$\det |F_{\alpha\beta}| = [e^{[\phi+\Lambda](r)} r^2 \sin \theta (B^r E_r + B^\theta E_\theta + B^\varphi E_\varphi)]^2$$

(B.1)

Matrik kofaktor dari tensor kuat-medan elektromagnetik  $F_{\alpha\beta}$  adalah

$$C = \begin{bmatrix} C_{00} & C_{01} & C_{02} & C_{03} \\ C_{10} & C_{11} & C_{12} & C_{13} \\ C_{20} & C_{21} & C_{22} & C_{23} \\ C_{30} & C_{31} & C_{32} & C_{33} \end{bmatrix} \quad (\text{B.2})$$

dengan nilai tiap-tiap komponennya

5. Baris pertama

$$C_{00} = \begin{bmatrix} 0 & e^{\Lambda(r)} r^2 \sin \theta B^\varphi & -e^{\Lambda(r)} r^2 \sin \theta B^\theta \\ -e^{\Lambda(r)} r^2 \sin \theta B^\varphi & 0 & e^{\Lambda(r)} r^2 \sin \theta B^r \\ e^{\Lambda(r)} r^2 \sin \theta B^\theta & -e^{\Lambda(r)} r^2 \sin \theta B^r & 0 \end{bmatrix}$$

$$C_{00} = [0 + e^{3\Lambda(r)} (r^2 \sin \theta) B^\varphi B^r B^\theta - e^{3\Lambda(r)} (r^2 \sin \theta) B^\theta B^r B^\varphi] - [0 + 0 + 0] = 0 \quad (\text{B.3})$$

$$C_{01} = - \begin{bmatrix} e^{\phi(r)} E_r & e^{\Lambda(r)} r^2 \sin \theta B^\varphi & -e^{\Lambda(r)} r^2 \sin \theta B^\theta \\ e^{\phi(r)} E_\theta & 0 & e^{\Lambda(r)} r^2 \sin \theta B^r \\ e^{\phi(r)} E_\varphi & -e^{\Lambda(r)} r^2 \sin \theta B^r & 0 \end{bmatrix}$$

$$C_{01} = -\{[0 + e^{[\phi+2\Lambda](r)} (r^2 \sin \theta)^2 B^\varphi B^r E_\varphi + e^{[\phi+2\Lambda](r)} (r^2 \sin \theta)^2 B^\theta B^r E_\theta]$$

$$- [0 + 0 - e^{[\phi+2\Lambda](r)} (r^2 \sin \theta)^2 B^r B^r E_r]\}$$

$$= -e^{[\phi+2\Lambda](r)} (r^2 \sin \theta)^2 B^r (B^r E_r + B^\theta E_\theta + B^\varphi E_\varphi) \quad (\text{B.4})$$

$$C_{02} = \begin{bmatrix} e^{\phi(r)} E_r & 0 & -e^{\Lambda(r)} r^2 \sin \theta B^\theta \\ e^{\phi(r)} E_\theta & -e^{\Lambda(r)} r^2 \sin \theta B^\varphi & e^{\Lambda(r)} r^2 \sin \theta B^r \\ e^{\phi(r)} E_\varphi & e^{\Lambda(r)} r^2 \sin \theta B^\theta & 0 \end{bmatrix}$$

$$\begin{aligned}
C_{02} &= [0 + 0 - e^{[\phi+2\Lambda](r)}(r^2 \sin \theta)^2 B^\theta B^\theta E_\theta] \\
&\quad - [e^{[\phi+2\Lambda](r)}(r^2 \sin \theta)^2 B^\theta B^\varphi E_\varphi + 0 \\
&\quad + e^{[\phi+2\Lambda](r)}(r^2 \sin \theta)^2 B^\theta B^r E_r] \\
&= -e^{[\phi+2\Lambda](r)}(r^2 \sin \theta)^2 B^\theta (B^r E_r + B^\theta E_\theta + B^\varphi E_\varphi)
\end{aligned} \tag{B.5}$$

$$\begin{aligned}
C_{03} &= - \begin{bmatrix} e^{\phi(r)} E_r & 0 & e^{\Lambda(r)} r^2 \sin \theta B^\varphi \\ e^{\phi(r)} E_\theta & -e^{\Lambda(r)} r^2 \sin \theta B^\varphi & 0 \\ e^{\phi(r)} E_\varphi & e^{\Lambda(r)} r^2 \sin \theta B^\theta & -e^{\Lambda(r)} r^2 \sin \theta B^r \end{bmatrix} \\
C_{03} &= -\{[e^{[\phi+2\Lambda](r)}(r^2 \sin \theta)^2 B^\varphi B^r E_r + 0 + e^{[\phi+2\Lambda](r)}(r^2 \sin \theta)^2 B^\varphi B^\theta E_\theta] \\
&\quad - [-e^{[\phi+2\Lambda](r)}(r^2 \sin \theta)^2 B^\varphi B^\varphi E_\varphi + 0 + 0]\} \\
&= -e^{[\phi+2\Lambda](r)}(r^2 \sin \theta)^2 B^\varphi (B^r E_r + B^\theta E_\theta + B^\varphi E_\varphi)
\end{aligned} \tag{B.6}$$

6. Baris kedua

$$\begin{aligned}
C_{01} &= - \begin{bmatrix} -e^{\phi(r)} E_r & -e^{\phi(r)} E_\theta & -e^{\phi(r)} E_\varphi \\ -e^{\Lambda(r)} r^2 \sin \theta B^\varphi & 0 & e^{\Lambda(r)} r^2 \sin \theta B^r \\ e^{\Lambda(r)} r^2 \sin \theta B^\theta & -e^{\Lambda(r)} r^2 \sin \theta B^r & 0 \end{bmatrix} \\
C_{01} &= -\{[0 - e^{[\phi+2\Lambda](r)}(r^2 \sin \theta)^2 B^\theta B^r E_\theta - e^{[\phi+2\Lambda](r)}(r^2 \sin \theta)^2 B^r B^\varphi E_\varphi] \\
&\quad - [0 + 0 + e^{[\phi+2\Lambda](r)}(r^2 \sin \theta)^2 B^r B^r E_r]\} \\
&= -e^{[\phi+2\Lambda](r)}(r^2 \sin \theta)^2 B^r (B^r E_r + B^\theta E_\theta + B^\varphi E_\varphi)
\end{aligned} \tag{B.7}$$

$$C_{11} = \begin{bmatrix} 0 & -e^{\phi(r)} E_\theta & -e^{\phi(r)} E_\varphi \\ e^{\phi(r)} E_\theta & 0 & e^{\Lambda(r)} r^2 \sin \theta B^r \\ -e^{\phi(r)} E_\varphi & -e^{\Lambda(r)} r^2 \sin \theta B^r & 0 \end{bmatrix}$$

$$\begin{aligned}
C_{11} &= [0 - e^{[2\phi+\Lambda](r)}(r^2 \sin \theta) B^r E_\theta E_\phi + e^{[2\phi+\Lambda](r)}(r^2 \sin \theta) B^r E_\theta E_\phi] \\
&\quad - [0 + 0 + 0] = 0
\end{aligned} \tag{B.8}$$

$$\begin{aligned}
C_{12} &= - \begin{bmatrix} 0 & -e^{\phi(r)} E_r & -e^{\phi(r)} E_\phi \\ e^{\phi(r)} E_\theta & -e^{\Lambda(r)} r^2 \sin \theta B^\phi & e^{\Lambda(r)} r^2 \sin \theta B^r \\ e^{\phi(r)} E_\phi & e^{\Lambda(r)} r^2 \sin \theta B^\theta & 0 \end{bmatrix} \\
C_{12} &= -\{[0 - e^{[2\phi+\Lambda](r)} r^2 \sin \theta B^r E_r E_\phi - e^{[2\phi+\Lambda](r)} r^2 \sin \theta B^\theta E_\theta E_\phi] \\
&\quad - [e^{[2\phi+\Lambda](r)} r^2 \sin \theta B^\phi E_\phi E_\phi + 0 + 0]\} \\
&= e^{[2\phi+\Lambda](r)} r^2 \sin \theta E_\phi (B^r E_r + B^\theta E_\theta + B^\phi E_\phi)
\end{aligned} \tag{B.9}$$

$$\begin{aligned}
C_{13} &= \begin{bmatrix} 0 & -e^{\phi(r)} E_r & -e^{\phi(r)} E_\theta \\ e^{\phi(r)} E_\theta & -e^{\Lambda(r)} r^2 \sin \theta B^\phi & 0 \\ e^{\phi(r)} E_\phi & e^{\Lambda(r)} r^2 \sin \theta B^\theta & -e^{\Lambda(r)} r^2 \sin \theta B^r \end{bmatrix} \\
C_{13} &= [0 + 0 - e^{[2\phi+\Lambda](r)}(r^2 \sin \theta) B^\theta E_\theta E_\theta] \\
&\quad - [e^{[2\phi+\Lambda](r)}(r^2 \sin \theta) B^\phi E_\phi E_\theta + e^{[2\phi+\Lambda](r)}(r^2 \sin \theta) B^r E_r E_\theta + 0] \\
&= -e^{[2\phi+\Lambda](r)} r^2 \sin \theta - \theta E_\theta (B^r E_r + B^\theta E_\theta + B^\phi E_\phi)
\end{aligned} \tag{B.10}$$

7. Baris ketiga

$$C_{20} = \begin{bmatrix} -e^{\phi(r)} E_r & -e^{\phi(r)} E_\theta & -e^{\phi(r)} E_\phi \\ 0 & e^{\Lambda(r)} r^2 \sin \theta B^\phi & -e^{\Lambda(r)} r^2 \sin \theta B^\theta \\ e^{\Lambda(r)} r^2 \sin \theta B^\theta & -e^{\Lambda(r)} r^2 \sin \theta B^r & 0 \end{bmatrix}$$

$$\begin{aligned}
C_{20} &= [0 + e^{[\phi+2\Lambda](r)}(r^2 \sin \theta)^2 B^\theta B^\theta E_\theta + 0] \\
&\quad - [-e^{[\phi+2\Lambda](r)}(r^2 \sin \theta)^2 B^\theta B^\varphi E_\varphi + 0] \\
&\quad - e^{[\phi+2\Lambda](r)}(r^2 \sin \theta)^2 B^\theta B^r E_r] \\
&= e^{[\phi+2\Lambda](r)}(r^2 \sin \theta)^2 B^\theta (B^r E_r + B^\theta E_\theta + B^\varphi E_\varphi)
\end{aligned} \tag{B.11}$$

$$\begin{aligned}
C_{21} &= - \begin{bmatrix} 0 & -e^{\phi(r)} E_\theta & -e^{\phi(r)} E_\varphi \\ e^{\phi(r)} E_r & e^{\Lambda(r)} r^2 \sin \theta B^\varphi & -e^{\Lambda(r)} r^2 \sin \theta B^\theta \\ e^{\phi(r)} E_\varphi & -e^{\Lambda(r)} r^2 \sin \theta B^r & 0 \end{bmatrix} \\
C_{21} &= -\{[0 + e^{[2\phi+\Lambda](r)} r^2 \sin \theta B^\theta E_\theta E_\varphi + e^{[2\phi+\Lambda](r)} r^2 \sin \theta B^r E_r E_\varphi] \\
&\quad - [-e^{[2\phi+\Lambda](r)} r^2 \sin \theta B^\varphi E_\varphi E_\varphi + 0 + 0]\} \\
&= -e^{[2\phi+\Lambda](r)} r^2 \sin \theta E_\varphi (B^r E_r + B^\theta E_\theta + B^\varphi E_\varphi)
\end{aligned} \tag{B.12}$$

$$\begin{aligned}
C_{22} &= \begin{bmatrix} 0 & -e^{\phi(r)} E_r & -e^{\phi(r)} E_\varphi \\ e^{\phi(r)} E_r & 0 & -e^{\Lambda(r)} r^2 \sin \theta B^\theta \\ e^{\phi(r)} E_\varphi & e^{\Lambda(r)} r^2 \sin \theta B^\theta & 0 \end{bmatrix} \\
C_{22} &= [0 + e^{[2\phi+\Lambda](r)} r^2 \sin \theta B^\theta E_r E_\varphi - e^{[2\phi+\Lambda](r)} r^2 \sin \theta B^\theta E_r E_\varphi] - [0 + 0 + 0] \\
&= 0
\end{aligned} \tag{B.13}$$

$$\begin{aligned}
C_{23} &= - \begin{bmatrix} 0 & -e^{\phi(r)} E_r & -e^{\phi(r)} E_\theta \\ e^{\phi(r)} E_r & 0 & e^{\Lambda(r)} r^2 \sin \theta B^\varphi \\ e^{\phi(r)} E_\varphi & e^{\Lambda(r)} r^2 \sin \theta B^\theta & -e^{\Lambda(r)} r^2 \sin \theta B^r \end{bmatrix} \\
C_{23} &= -\{[0 - e^{[2\phi+\Lambda](r)} r^2 \sin \theta B^\varphi E_\varphi E_r - e^{[2\phi+\Lambda](r)} r^2 \sin \theta B^\theta E_\theta E_r] \\
&\quad - [0 + e^{[2\phi+\Lambda](r)} r^2 \sin \theta B^r E_r E_r + 0]\} \\
&= e^{[2\phi+\Lambda](r)} r^2 \sin \theta E_r (B^r E_r + B^\theta E_\theta + B^\varphi E_\varphi)
\end{aligned} \tag{B.14}$$

8. Baris keempat

$$\begin{aligned}
 C_{30} &= - \begin{bmatrix} -e^{\phi(r)} E_r & -e^{\phi(r)} E_\theta & -e^{\phi(r)} E_\varphi \\ 0 & e^{\Lambda(r)} r^2 \sin \theta B^\varphi & -e^{\Lambda(r)} r^2 \sin \theta B^\theta \\ -e^{\Lambda(r)} r^2 \sin \theta B^\varphi & 0 & e^{\Lambda(r)} r^2 \sin \theta B^r \end{bmatrix} \\
 C_{30} &= - \{ [-e^{[\phi+2\Lambda](r)} (r^2 \sin \theta)^2 B^\varphi B^r E_r - e^{[2\phi+\Lambda](r)} (r^2 \sin \theta)^2 B^\varphi B^\theta E_\theta + 0] \\
 &\quad - [e^{[2\phi+\Lambda](r)} (r^2 \sin \theta)^2 B^\varphi B^\varphi E_\varphi + 0 + 0] \} \\
 &= -e^{[2\phi+\Lambda](r)} (r^2 \sin \theta)^2 B^\varphi (B^r E_r + B^\theta E_\theta + B^\varphi E_\varphi)
 \end{aligned} \tag{B.15}$$

$$\begin{aligned}
 C_{31} &= \begin{bmatrix} 0 & -e^{\phi(r)} E_\theta & -e^{\phi(r)} E_\varphi \\ e^{\phi(r)} E_r & e^{\Lambda(r)} r^2 \sin \theta B^\varphi & -e^{\Lambda(r)} r^2 \sin \theta B^\theta \\ e^{\phi(r)} E_\theta & 0 & e^{\Lambda(r)} r^2 \sin \theta B^r \end{bmatrix} \\
 C_{31} &= [0 + e^{[2\phi+\Lambda](r)} r^2 \sin \theta B^\theta E_\theta E_\theta + 0] \\
 &\quad - [-e^{[2\phi+\Lambda](r)} r^2 \sin \theta B^\varphi E_\varphi E_\theta - e^{[2\phi+\Lambda](r)} r^2 \sin \theta B^r E_r E_\theta + 0] \\
 &= e^{[2\phi+\Lambda](r)} r^2 \sin \theta E_\theta (B^r E_r + B^\theta E_\theta + B^\varphi E_\varphi)
 \end{aligned} \tag{B.16}$$

$$\begin{aligned}
 C_{32} &= - \begin{bmatrix} 0 & -e^{\phi(r)} E_r & -e^{\phi(r)} E_\varphi \\ e^{\phi(r)} E_r & 0 & -e^{\Lambda(r)} r^2 \sin \theta B^\theta \\ e^{\phi(r)} E_\theta & -e^{\Lambda(r)} r^2 \sin \theta B^\varphi & e^{\Lambda(r)} r^2 \sin \theta B^r \end{bmatrix} \\
 C_{32} &= - \{ [0 + e^{[2\phi+\Lambda](r)} r^2 \sin \theta B^\theta E_\theta E_r + e^{[2\phi+\Lambda](r)} r^2 \sin \theta B^\varphi E_\varphi E_r] \\
 &\quad - [0 - e^{[2\phi+\Lambda](r)} r^2 \sin \theta B^r E_r E_r + 0] \} \\
 &= -e^{[2\phi+\Lambda](r)} r^2 \sin \theta E_r (B^r E_r + B^\theta E_\theta + B^\varphi E_\varphi)
 \end{aligned} \tag{B.17}$$



$$\begin{aligned}
C_{33} &= \begin{bmatrix} 0 & -e^{\phi(r)} E_r & -e^{\phi(r)} E_\theta \\ e^{\phi(r)} E_r & 0 & e^{\Lambda(r)} r^2 \sin \theta B^\varphi \\ e^{\phi(r)} E_\theta & -e^{\Lambda(r)} r^2 \sin \theta B^\varphi & 0 \end{bmatrix} \\
C_{33} &= -\{[0 - e^{[2\phi+\Lambda](r)} r^2 \sin \theta B^\varphi E_\theta E_r + e^{[2\phi+\Lambda](r)} r^2 \sin \theta B^\varphi E_\theta E_r] \\
&\quad - [0 + 0 + 0]\} = 0
\end{aligned} \tag{B.18}$$

Maka transpos dari matrik kovaktornya diberikan oleh

$$C^T = \begin{bmatrix} C_{00} & C_{10} & C_{20} & C_{30} \\ C_{01} & C_{11} & C_{21} & C_{31} \\ C_{02} & C_{12} & C_{22} & C_{32} \\ C_{03} & C_{13} & C_{23} & C_{33} \end{bmatrix} = (B^r E_r + B^\theta E_\theta + B^\varphi E_\varphi) \begin{bmatrix} C_{00}' & C_{10}' & C_{20}' & C_{30}' \\ C_{01}' & C_{11}' & C_{21}' & C_{31}' \\ C_{02}' & C_{12}' & C_{22}' & C_{32}' \\ C_{03}' & C_{13}' & C_{23}' & C_{33}' \end{bmatrix} \tag{B.19}$$

dengan

$$\begin{aligned}
C_{00}' &= C_{11}' = C_{22}' = C_{33}' = 0 \\
C_{01}' &= -e^{[\phi+2\Lambda](r)} (r^2 \sin \theta)^2 B^r = -C_{10}' \\
C_{02}' &= -e^{[\phi+2\Lambda](r)} (r^2 \sin \theta)^2 B^\theta = -C_{20}' \\
C_{03}' &= -e^{[\phi+2\Lambda](r)} (r^2 \sin \theta)^2 B^\varphi = -C_{30}' \\
C_{12}' &= e^{[2\phi+\Lambda](r)} r^2 \sin \theta E_\varphi = -C_{21}' \\
C_{13}' &= -e^{[2\phi+\Lambda](r)} r^2 \sin \theta E_\theta = -C_{31}' \\
C_{32}' &= -e^{[2\phi+\Lambda](r)} r^2 \sin \theta E_r = -C_{23}'
\end{aligned} \tag{B.20}$$

sedemikian rupa sehingga tensor kuat-medan elektromagnetik kontravarian adalah

$$\begin{aligned}
F^{\alpha\beta} &= \frac{C^T}{\det |F_{\alpha\beta}|} \\
&= \frac{(B^r E_r + B^\theta E_\theta + B^\varphi E_\varphi)}{[e^{[\phi+\Lambda](r)} r^2 \sin \theta (B^r E_r + B^\theta E_\theta + B^\varphi E_\varphi)]^2} \begin{bmatrix} C_{00}' & C_{10}' & C_{20}' & C_{30}' \\ C_{01}' & C_{11}' & C_{21}' & C_{31}' \\ C_{02}' & C_{12}' & C_{22}' & C_{32}' \\ C_{03}' & C_{13}' & C_{23}' & C_{33}' \end{bmatrix}
\end{aligned} \tag{B.20}$$

Dengan menuliskan  $\beta = [e^{[\phi+\Lambda](r)} r^2 \sin \theta]^2$  dan memasukkan nilai ini ke dalam matriks (B.21), maka didapat

$$F^{\alpha\beta} = \frac{1}{(B^r E_r + B^\theta E_\theta + B^\varphi E_\varphi)} \begin{bmatrix} \frac{C_{00}'}{\beta} & \frac{C_{10}'}{\beta} & \frac{C_{20}'}{\beta} & \frac{C_{30}'}{\beta} \\ \frac{C_{01}'}{\beta} & \frac{C_{11}'}{\beta} & \frac{C_{21}'}{\beta} & \frac{C_{31}'}{\beta} \\ \frac{C_{02}'}{\beta} & \frac{C_{12}'}{\beta} & \frac{C_{22}'}{\beta} & \frac{C_{32}'}{\beta} \\ \frac{C_{03}'}{\beta} & \frac{C_{13}'}{\beta} & \frac{C_{23}'}{\beta} & \frac{C_{33}'}{\beta} \end{bmatrix} \tag{B.21}$$

dengan

$$F'^{00} = \frac{C_{00}'}{\beta} = 0$$

$$F'^{11} = \frac{C_{11}'}{\beta} = 0$$

$$F'^{22} = \frac{C_{22}'}{\beta} = 0$$

$$F'^{33} = \frac{C_{33}'}{\beta} = 0$$

$$\begin{aligned}
F'^{01} &= \frac{C_{01}'}{\beta} = \frac{-e^{[\phi+2\Lambda](r)}(r^2 \sin \theta)^2 B^r}{[e^{[\phi+\Lambda](r)} r^2 \sin \theta]^2} = -e^{-\phi(r)} B^r = -\frac{C_{10}'}{\beta} = -F'^{10} \\
F'^{02} &= \frac{C_{02}'}{\beta} = \frac{-e^{[\phi+2\Lambda](r)}(r^2 \sin \theta)^2 B^\theta}{[e^{[\phi+\Lambda](r)} r^2 \sin \theta]^2} = -e^{-\phi(r)} B^\theta = -\frac{C_{20}'}{\beta} = -F'^{20} \\
F'^{03} &= \frac{C_{03}'}{\beta} = \frac{-e^{[\phi+2\Lambda](r)}(r^2 \sin \theta)^2 B^\varphi}{[e^{[\phi+\Lambda](r)} r^2 \sin \theta]^2} = -e^{-\phi(r)} B^\varphi = -\frac{C_{30}'}{\beta} = -F'^{30} \\
F'^{12} &= \frac{C_{12}'}{\beta} = \frac{e^{[2\phi+\Lambda](r)} r^2 \sin \theta E_\varphi}{[e^{[\phi+\Lambda](r)} r^2 \sin \theta]^2} = e^{-\Lambda(r)} (r^2 \sin \theta)^{-1} E_\varphi = -\frac{C_{21}'}{\beta} = -F'^{21} \\
F'^{13} &= \frac{C_{13}'}{\beta} = \frac{-e^{[2\phi+\Lambda](r)} r^2 \sin \theta E_\theta}{[e^{[\phi+\Lambda](r)} r^2 \sin \theta]^2} = -e^{-\Lambda(r)} (r^2 \sin \theta)^{-1} E_\theta = -\frac{C_{31}'}{\beta} = -F'^{31} \\
F'^{32} &= \frac{C_{32}'}{\beta} = \frac{-e^{[2\phi+\Lambda](r)} r^2 \sin \theta E_r}{[e^{[\phi+\Lambda](r)} r^2 \sin \theta]^2} = -e^{-\Lambda(r)} (r^2 \sin \theta)^{-1} E_r = -\frac{C_{23}'}{\beta} = -F'^{23}
\end{aligned}$$

dan

$$(B^r E_r + B^\theta E_\theta + B^\varphi E_\varphi) = (B^i E_i)$$

maka persamaan (B.21) menjadi

$$F^{\alpha\beta} = \frac{1}{(B^i E_i)} \begin{bmatrix} F'^{00} & F'^{10} & F'^{20} & F'^{30} \\ F'^{01} & F'^{11} & F'^{21} & F'^{31} \\ F'^{02} & F'^{12} & F'^{22} & F'^{32} \\ F'^{03} & F'^{13} & F'^{23} & F'^{33} \end{bmatrix}. \tag{B.22}$$

Dengan mensubstitusikan persamaan (B.22) ke persamaan (2.135), maka didapatkan medan listrik, yaitu

$$E^\mu = F^{\mu\nu} u_\nu. \tag{B.23}$$

Mengingat kecepatan-4  $u_0 = e^{\phi(r)}$ ,  $u_1 = 0$ ,  $u_2 = 0$  dan  $u_3 = 0$ , maka komponen medan listriknya adalah

4. Komponen radial

$$E^r = E^1 = F^{rv}u_v = F^{10}u_0 + F^{11}u_1 + F^{12}u_2 + F^{13}u_3 = F^{10}u_0$$

$$E^r = \frac{e^{-\phi(r)}B^r}{(B^iE_i)} e^{\phi(r)}$$

$$E^r = \frac{B^r}{(B^iE_i)}$$

(B.24)

5. Komponen polar

$$E^\theta = E^2 = F^{\theta v}u_v = F^{20}u_0 + F^{21}u_1 + F^{22}u_2 + F^{23}u_3 = F^{20}u_0$$

$$E^\theta = \frac{e^{-\phi(r)}B^\theta}{(B^iE_i)} e^{\phi(r)}$$

$$E^\theta = \frac{B^\theta}{(B^iE_i)}$$

(B.25)

6. Komponen toroidal

$$E^\phi = E^3 = F^{\phi v}u_v = F^{30}u_0 + F^{31}u_1 + F^{32}u_2 + F^{33}u_3 = F^{30}u_0$$

$$E^\varphi = \frac{e^{-\phi(r)} B^\varphi}{(B^i E_i)} e^{\phi(r)}$$

$$E^\varphi = \frac{B^\varphi}{(B^i E_i)}$$

(B.26)

Selanjutnya diketahui dari persamaan (2.136)

$$B_\alpha = F_{\alpha\beta} u^\beta = \frac{1}{2} \eta_{\alpha\beta\gamma\delta} u^\beta F^{\gamma\delta} = \frac{1}{2} \sqrt{-g} \epsilon_{\alpha\beta\gamma\delta} u^\beta F^{\gamma\delta}$$

$$B_\alpha = \frac{1}{2} e^{[\phi+\Lambda](r)} r^2 \sin \theta \epsilon_{\alpha\beta\gamma\delta} u^\beta F^{\gamma\delta}$$

(B.27)

Maka komponen medan magnetnya

4. Komponen radial

$$B_r = B_1 = \frac{1}{2} e^{[\phi+\Lambda](r)} r^2 \sin \theta (\epsilon_{1023} u^0 F^{23} + \epsilon_{1032} u^0 F^{32} + \epsilon_{1203} u^2 F^{03}$$

$$+ \epsilon_{1230} u^2 F^{30} + \epsilon_{1302} u^3 F^{02} + \epsilon_{1320} u^3 F^{20})$$

$$B_r = \frac{1}{2} e^{[\phi+\Lambda](r)} r^2 \sin \theta (\epsilon_{1023} u^0 F^{23} + \epsilon_{1032} u^0 F^{32})$$

Dengan  $\epsilon_{1023} = -\epsilon_{0123} = -1$  dan  $\epsilon_{1032} = -\epsilon_{1023} = -(-\epsilon_{0123}) = +1$ , maka

$$B_r = \frac{1}{2} e^{[\phi+\Lambda](r)} r^2 \sin \theta \frac{e^{-\phi(r)}}{(B^i E_i)} (-e^{-\Lambda(r)} (r^2 \sin \theta)^{-1} E_r - e^{-\Lambda(r)} (r^2 \sin \theta)^{-1} E_r)$$

$$B_r = \frac{1}{2} e^{[\phi+\Lambda](r)} r^2 \sin \theta \frac{e^{-\phi(r)}}{(B^i E_i)} \left( -2e^{-\Lambda(r)} (r^2 \sin \theta)^{-1} E_r \right)$$

$$B_r = -\frac{E_r}{(B^i E_i)}$$

(B.28)

### 5. Komponen polar

$$B_\theta = B_2 = \frac{1}{2} e^{[\phi+\Lambda](r)} r^2 \sin \theta \left( \epsilon_{2013} u^0 F^{13} + \epsilon_{2031} u^0 F^{31} + \epsilon_{2103} u^1 F^{03} \right. \\ \left. + \epsilon_{2130} u^1 F^{30} + \epsilon_{2301} u^3 F^{01} + \epsilon_{2310} u^3 F^{10} \right)$$

$$B_r = \frac{1}{2} e^{[\phi+\Lambda](r)} r^2 \sin \theta \left( \epsilon_{2013} u^0 F^{13} + \epsilon_{2031} u^0 F^{31} \right)$$

Dengan  $\epsilon_{2013} = -\epsilon_{0213} = -(-\epsilon_{0123}) = +1$  dan  $\epsilon_{2031} = -\epsilon_{0231} = -(-\epsilon_{0132}) = -\epsilon_{0123} = -1$ , maka

$$B_\theta = \frac{1}{2} e^{[\phi+\Lambda](r)} r^2 \sin \theta \frac{e^{-\phi(r)}}{(B^i E_i)} \left( -e^{-\Lambda(r)} (r^2 \sin \theta)^{-1} E_\theta - e^{-\Lambda(r)} (r^2 \sin \theta)^{-1} E_\theta \right)$$

$$B_\theta = \frac{1}{2} e^{[\phi+\Lambda](r)} r^2 \sin \theta \frac{e^{-\phi(r)}}{(B^i E_i)} \left( -2e^{-\Lambda(r)} (r^2 \sin \theta)^{-1} E_\theta \right)$$

$$B_\theta = -\frac{E_\theta}{(B^i E_i)}$$

(B.29)

### 6. Komponen toroidal

$$B_\varphi = B_3 = \frac{1}{2} e^{[\phi+\Lambda](r)} r^2 \sin \theta \left( \epsilon_{3012} u^0 F^{12} + \epsilon_{3021} u^0 F^{21} + \epsilon_{3102} u^1 F^{02} \right. \\ \left. + \epsilon_{3120} u^1 F^{20} + \epsilon_{3201} u^2 F^{01} + \epsilon_{3210} u^2 F^{10} \right)$$

$$B_\varphi = \frac{1}{2} e^{[\phi+\Lambda](r)} r^2 \sin \theta \left( \epsilon_{3012} u^0 F^{12} + \epsilon_{3021} u^0 F^{21} \right)$$

Dengan  $\epsilon_{3012} = -\epsilon_{0312} = -(-\epsilon_{0132}) = -\epsilon_{0123} = -1$  dan  $\epsilon_{3021} = -\epsilon_{0321} = -(-\epsilon_{0123}) = +1$ , maka

$$\begin{aligned}
 B_\varphi &= \frac{1}{2} e^{[\phi+\Lambda](r)} r^2 \sin \theta \frac{e^{-\phi(r)}}{(B^i E_i)} \left( -e^{-\Lambda(r)} (r^2 \sin \theta)^{-1} E_\varphi - e^{-\Lambda(r)} (r^2 \sin \theta)^{-1} E_\varphi \right) \\
 B_\varphi &= \frac{1}{2} e^{[\phi+\Lambda](r)} r^2 \sin \theta - \theta \frac{e^{-\phi(r)}}{(B^i E_i)} \left( -2e^{-\Lambda(r)} (r^2 \sin \theta)^{-1} E_\varphi \right) \\
 B_\varphi &= -\frac{E_\varphi}{(B^i E_i)}
 \end{aligned}
 \tag{B.30}$$

Oleh karena itu, tensor kuat-medan elektromagnetik kontravarian adalah

$$F^{\alpha\beta} = \begin{bmatrix} F^{00} & F^{10} & F^{20} & F^{30} \\ F^{01} & F^{11} & F^{21} & F^{31} \\ F^{02} & F^{12} & F^{22} & F^{32} \\ F^{03} & F^{13} & F^{23} & F^{33} \end{bmatrix}
 \tag{B.31}$$

dengan

$$\begin{aligned}
 F^{00} &= F^{11} = F^{22} = F^{33} = 0 \\
 F^{01} &= \frac{F'^{01}}{(B^i E_i)} = \frac{e^{-\phi(r)} B_r}{(B^i E_i)} = e^{-\phi(r)} E^r = -F^{10} \\
 F^{02} &= \frac{F'^{02}}{(B^i E_i)} = \frac{e^{-\phi(r)} B_\theta}{(B^i E_i)} = e^{-\phi(r)} E^\theta = -F^{20} \\
 F^{03} &= \frac{F'^{03}}{(B^i E_i)} = \frac{e^{-\phi(r)} B_\varphi}{(B^i E_i)} = e^{-\phi(r)} E^\varphi = -F^{30}
 \end{aligned}$$

$$\begin{aligned}
F^{12} &= \frac{F'^{12}}{(B^i E_i)} = \frac{e^{-\Lambda(r)}(r^2 \sin \theta)^{-1} E_\phi}{(B^i E_i)} = -e^{-\Lambda(r)}(r^2 \sin \theta)^{-1} B_\phi = -F^{21} \\
F^{13} &= \frac{F'^{13}}{(B^i E_i)} = \frac{-e^{-\Lambda(r)}(r^2 \sin \theta)^{-1} E_\theta}{(B^i E_i)} = e^{-\Lambda(r)}(r^2 \sin \theta)^{-1} B_\theta = -F^{31} \\
F^{32} &= \frac{F'^{32}}{(B^i E_i)} = \frac{-e^{-\Lambda(r)}(r^2 \sin \theta)^{-1} E_r}{(B^i E_i)} = e^{-\Lambda(r)}(r^2 \sin \theta)^{-1} B_r = -F^{23}
\end{aligned}
\tag{B.32}$$

Dari persamaan (2.133), komponen rapat arus-4 adalah

$$J^\alpha = \rho_e u^\alpha + j^\alpha = \rho_e u^\alpha + \sigma F_{\alpha\beta} u^\beta \tag{B.33}$$

#### 5. Komponen waktu

$$\begin{aligned}
J^t &= \rho_e u^0 + \sigma(F_{00}u^0 + F_{01}u^1 + F_{02}u^2 + F_{03}u^3) = \rho_e u^0 + \sigma F_{00}u^0 = \rho_e u^0 \\
&= \rho_e e^{-\phi(r)}
\end{aligned}
\tag{B.34}$$

#### 6. Komponen radial

$$\begin{aligned}
J^r &= \rho_e u^1 + \sigma(F_{10}u^0 + F_{11}u^1 + F_{12}u^2 + F_{13}u^3) = \sigma F_{10}u^0 = \sigma e^{\phi(r)} E_r e^{-\phi(r)} \\
&= \sigma E_r
\end{aligned}
\tag{B.35}$$

#### 7. Komponen polar

$$\begin{aligned}
J^\theta &= \rho_e u^2 + \sigma(F_{20}u^0 + F_{21}u^1 + F_{22}u^2 + F_{23}u^3) = \sigma F_{20}u^0 = \sigma e^{\phi(r)} E_\theta e^{-\phi(r)} \\
&= \sigma E_\theta
\end{aligned}
\tag{B.36}$$



8. Komponen toroidal

$$\begin{aligned}
 J^\varphi &= \rho_e u^3 + \sigma(F_{30}u^0 + F_{31}u^1 + F_{32}u^2 + F_{33}u^3) = \sigma F_{30}u^0 = \sigma e^{\phi(r)} E_\varphi e^{-\phi(r)} \\
 &= \sigma E_\varphi
 \end{aligned}
 \tag{B.37}$$

Dari semua hasil di atas, maka Persamaan Maxwell II pada (2.132) dapat diturunkan

$$F_{;\beta}^{\alpha\beta} = \frac{1}{\sqrt{-g}} (\sqrt{-g} F^{\alpha\beta})_{,\beta} = 4\pi J^\alpha$$

atau

$$F_{;\beta}^{\alpha\beta} = (\sqrt{-g} F^{\alpha\beta})_{,\beta} = \sqrt{-g} 4\pi J^\alpha \tag{B.38}$$

5. Untuk  $\alpha = 0$

$$\begin{aligned}
 F_{;0}^{00} + F_{;1}^{01} + F_{;2}^{02} + F_{;3}^{03} &= \sqrt{-g} 4\pi J^0 \\
 (\sqrt{-g} F^{00})_{,0} + (\sqrt{-g} F^{01})_{,1} + (\sqrt{-g} F^{02})_{,2} + (\sqrt{-g} F^{03})_{,3} &= \sqrt{-g} 4\pi J^0 \\
 [(e^{[\phi+\Lambda](r)} r^2 \sin \theta) 0]_{,t} + [(e^{[\phi+\Lambda](r)} r^2 \sin \theta) e^{-\phi(r)} E^r]_{,r} \\
 &+ [(e^{[\phi+\Lambda](r)} r^2 \sin \theta) e^{-\phi(r)} E^\theta]_{,\theta} \\
 &+ [(e^{[\phi+\Lambda](r)} r^2 \sin \theta) e^{-\phi(r)} E^\varphi]_{,\varphi} = 4\pi e^{[\phi+\Lambda](r)} r^2 \sin \theta J^t \\
 [e^{\Lambda(r)} r^2 \sin \theta E^r]_{,r} + [e^{\Lambda(r)} r^2 \sin \theta E^\theta]_{,\theta} + [e^{\Lambda(r)} r^2 \sin \theta E^\varphi]_{,\varphi} \\
 &= 4\pi e^{[\phi+\Lambda](r)} r^2 \sin \theta J^t \\
 [e^{\Lambda(r)} r^2 \sin \theta E^i]_{,i} &= 4\pi e^{[\phi+\Lambda](r)} r^2 \sin \theta J^t
 \end{aligned}
 \tag{B.39}$$

6. Untuk  $\alpha = 1$

$$\begin{aligned}
F_{;0}^{10} + F_{;1}^{11} + F_{;2}^{12} + F_{;3}^{13} &= \sqrt{-g} 4\pi J^1 \\
(\sqrt{-g} F^{10})_{,0} + (\sqrt{-g} F^{11})_{,1} + (\sqrt{-g} F^{12})_{,2} + (\sqrt{-g} F^{13})_{,3} &= \sqrt{-g} 4\pi J^1 \\
[-(e^{[\phi+\Lambda](r)} r^2 \sin \theta) e^{-\phi(r)} E^r]_{,t} + [(e^{[\phi+\Lambda](r)} r^2 \sin \theta) 0]_{,r} \\
&+ [-(e^{[\phi+\Lambda](r)} r^2 \sin \theta) e^{-\Lambda(r)} (r^2 \sin \theta)^{-1} B_\phi]_{,\theta} \\
&+ [(e^{[\phi+\Lambda](r)} r^2 \sin \theta) e^{-\Lambda(r)} (r^2 \sin \theta)^{-1} B_\theta]_{,\phi} \\
&= 4\pi e^{[\phi+\Lambda](r)} r^2 \sin \theta J^r \\
[-e^{\Lambda(r)} r^2 \sin \theta E^r]_{,t} + [-e^{\phi(r)} B_\phi]_{,\theta} + [e^{\phi(r)} B_\theta]_{,\phi} &= 4\pi e^{[\phi+\Lambda](r)} r^2 \sin \theta J^r \\
[-e^{\phi(r)} B_\phi]_{,\theta} + [e^{\phi(r)} B_\theta]_{,\phi} = [e^{\Lambda(r)} r^2 \sin \theta E^r]_{,t} + 4\pi e^{[\phi+\Lambda](r)} r^2 \sin \theta J^r \\
e^{\phi(r)} (B_{\theta,\phi} - B_{\phi,\theta}) &= e^{\Lambda(r)} r^2 \sin \theta \frac{\partial E^r}{\partial t} + 4\pi e^{[\phi+\Lambda](r)} r^2 \sin \theta J^r
\end{aligned} \tag{B.40}$$

7. Untuk  $\alpha = 2$

$$\begin{aligned}
F_{;0}^{20} + F_{;1}^{21} + F_{;2}^{22} + F_{;3}^{23} &= \sqrt{-g} 4\pi J^2 \\
(\sqrt{-g} F^{20})_{,0} + (\sqrt{-g} F^{21})_{,1} + (\sqrt{-g} F^{22})_{,2} + (\sqrt{-g} F^{23})_{,3} &= \sqrt{-g} 4\pi J^2 \\
[-(e^{[\phi+\Lambda](r)} r^2 \sin \theta) e^{-\phi(r)} E^\theta]_{,t} \\
&+ [(e^{[\phi+\Lambda](r)} r^2 \sin \theta) e^{-\Lambda(r)} (r^2 \sin \theta)^{-1} B_\phi]_{,r} \\
&+ [(e^{[\phi+\Lambda](r)} r^2 \sin \theta) 0]_{,\theta} \\
&+ [-(e^{[\phi+\Lambda](r)} r^2 \sin \theta) e^{-\Lambda(r)} (r^2 \sin \theta)^{-1} B_r]_{,\phi} \\
&= 4\pi e^{[\phi+\Lambda](r)} r^2 \sin \theta J^\theta
\end{aligned}$$

$$\begin{aligned}
& [-(e^{[\phi+\Lambda](r)} r^2 \sin \theta) e^{-\phi(r)} E^\theta]_{,t} \\
& \quad + [(e^{[\phi+\Lambda](r)} r^2 \sin \theta) e^{-\Lambda(r)} (r^2 \sin \theta)^{-1} B_\varphi]_{,r} \\
& \quad + [-(e^{[\phi+\Lambda](r)} r^2 \sin \theta) e^{-\Lambda(r)} (r^2 \sin \theta)^{-1} B_r]_{,\varphi} \\
& \quad = 4\pi e^{[\phi+\Lambda](r)} r^2 \sin \theta J^\theta \\
& [(e^{[\phi+\Lambda](r)} r^2 \sin \theta) e^{-\Lambda(r)} (r^2 \sin \theta)^{-1} B_\varphi]_{,r} \\
& \quad + [-(e^{[\phi+\Lambda](r)} r^2 \sin \theta) e^{-\Lambda(r)} (r^2 \sin \theta)^{-1} B_r]_{,\varphi} \\
& \quad = [-(e^{[\phi+\Lambda](r)} r^2 \sin \theta) e^{-\phi(r)} E^\theta]_{,t} + 4\pi e^{[\phi+\Lambda](r)} r^2 \sin \theta J^\theta \\
& [e^{\phi(r)} B_\varphi]_{,r} + [-e^{\phi(r)} B_r]_{,\varphi} \\
& \quad = [(e^{[\phi+\Lambda](r)} r^2 \sin \theta) e^{-\phi(r)} E^\theta]_{,t} + 4\pi e^{[\phi+\Lambda](r)} r^2 \sin \theta J^\theta \\
& e^{\phi(r)} (B_{\varphi,r} - B_{r,\varphi}) = e^{\Lambda(r)} r^2 \sin \theta \frac{\partial E^\theta}{\partial t} + 4\pi e^{[\phi+\Lambda](r)} r^2 \sin \theta J^\theta
\end{aligned} \tag{B.41}$$

8. Untuk  $\alpha = 3$

$$\begin{aligned}
& F_{;0}^{30} + F_{;1}^{31} + F_{;2}^{32} + F_{;3}^{33} = \sqrt{-g} 4\pi J^3 \\
& (\sqrt{-g} F^{30})_{,0} + (\sqrt{-g} F^{31})_{,1} + (\sqrt{-g} F^{32})_{,2} + (\sqrt{-g} F^{33})_{,3} = \sqrt{-g} 4\pi J^3 \\
& [-(e^{[\phi+\Lambda](r)} r^2 \sin \theta) e^{-\phi(r)} E^\varphi]_{,t} \\
& \quad + [-(e^{[\phi+\Lambda](r)} r^2 \sin \theta) e^{-\Lambda(r)} (r^2 \sin \theta)^{-1} B_\theta]_{,r} \\
& \quad + [(e^{[\phi+\Lambda](r)} r^2 \sin \theta) e^{-\Lambda(r)} (r^2 \sin \theta)^{-1} B_r]_{,\theta} \\
& \quad + [-(e^{[\phi+\Lambda](r)} r^2 \sin \theta) 0]_{,\varphi} = 4\pi e^{[\phi+\Lambda](r)} r^2 \sin \theta J^\varphi \\
& [-(e^{[\phi+\Lambda](r)} r^2 \sin \theta) e^{-\Lambda(r)} (r^2 \sin \theta)^{-1} B_\theta]_{,r} \\
& \quad + [(e^{[\phi+\Lambda](r)} r^2 \sin \theta) e^{-\Lambda(r)} (r^2 \sin \theta)^{-1} B_r]_{,\theta} \\
& \quad = [(e^{[\phi+\Lambda](r)} r^2 \sin \theta) e^{-\phi(r)} E^\varphi]_{,t} + 4\pi e^{[\phi+\Lambda](r)} r^2 \sin \theta J^\varphi
\end{aligned}$$

$$\begin{aligned}
& [-e^{\phi(r)} B_\theta]_{,r} + [e^{\phi(r)} B_r]_{,\theta} \\
& \quad = [(e^{[\phi+\Lambda](r)} r^2 \sin \theta) e^{-\phi(r)} E^\theta]_{,t} + 4\pi e^{[\phi+\Lambda](r)} r^2 \sin \theta J^\varphi \\
& e^{\phi(r)} (B_{r,\theta} - B_{\theta,r}) = e^{\Lambda(r)} r^2 \sin \theta \frac{\partial E^\varphi}{\partial t} + 4\pi e^{[\phi+\Lambda](r)} r^2 \sin \theta J^\varphi
\end{aligned}
\tag{B.42}$$

**LAMPIRAN C**  
**DINAMIKA MEDAN ELEKTROMAGNETIK RELATIVISTIK BINTANG**  
**NEUTRON STASIONER**

**A. Medan Listrik**

4. Komponen radial

Untuk medan listrik komponen radial, persamaan (B.35) disubstitusikan ke persamaan (B.40), yaitu

$$\begin{aligned}
 e^{\phi(r)}(B_{\theta,\varphi} - B_{\varphi,\theta}) &= e^{\Lambda(r)}r^2 \sin \theta \frac{\partial E^r}{\partial t} + 4\pi e^{[\phi+\Lambda](r)}r^2 \sin \theta \sigma E_r \\
 4\pi e^{[\phi+\Lambda](r)}r^2 \sin \theta \sigma E_r &= e^{\phi(r)}(B_{\theta,\varphi} - B_{\varphi,\theta}) - e^{\Lambda(r)}r^2 \sin \theta \frac{\partial E^r}{\partial t} \\
 E_r &= \frac{1}{4\pi e^{[\phi+\Lambda](r)}r^2 \sin \theta \sigma} \left[ e^{\phi(r)}(B_{\theta,\varphi} - B_{\varphi,\theta}) - e^{\Lambda(r)}r^2 \sin \theta \frac{\partial E^r}{\partial t} \right]
 \end{aligned} \tag{C.1}$$

5. Komponen polar

Untuk medan listrik komponen polar, persamaan (B.36) disubstitusikan ke persamaan (B.41), yaitu

$$\begin{aligned}
 e^{\phi(r)}(B_{\varphi,r} - B_{r,\varphi}) &= e^{\Lambda(r)}r^2 \sin \theta \frac{\partial E^\theta}{\partial t} + 4\pi e^{[\phi+\Lambda](r)}r^2 \sin \theta \sigma E_\theta \\
 4\pi e^{[\phi+\Lambda](r)}r^2 \sin \theta \sigma E_\theta &= e^{\phi(r)}(B_{\varphi,r} - B_{r,\varphi}) - e^{\Lambda(r)}r^2 \sin \theta \frac{\partial E^\theta}{\partial t} \\
 E_\theta &= \frac{1}{4\pi e^{[\phi+\Lambda](r)}r^2 \sin \theta \sigma} \left[ e^{\phi(r)}(B_{\varphi,r} - B_{r,\varphi}) - e^{\Lambda(r)}r^2 \sin \theta \frac{\partial E^\theta}{\partial t} \right]
 \end{aligned} \tag{C.2}$$

6. Komponen toroidal

Untuk medan listrik komponen polar, persamaan (B.37) disubstitusikan ke persamaan (B.42), yaitu

$$\begin{aligned}
e^{\phi(r)}(B_{r,\theta} - B_{\theta,r}) &= e^{\Lambda(r)}r^2 \sin \theta \frac{\partial E^\varphi}{\partial t} + 4\pi e^{[\phi+\Lambda](r)}r^2 \sin \theta \sigma E_\varphi \\
4\pi e^{[\phi+\Lambda](r)}r^2 \sin \theta \sigma E_\varphi &= e^{\phi(r)}(B_{r,\theta} - B_{\theta,r}) - e^{\Lambda(r)}r^2 \sin \theta \frac{\partial E^\varphi}{\partial t} \\
E_\varphi &= \frac{1}{4\pi e^{[\phi+\Lambda](r)}r^2 \sin \theta \sigma} \left[ e^{\phi(r)}(B_{r,\theta} - B_{\theta,r}) - e^{\Lambda(r)}r^2 \sin \theta \frac{\partial E^\varphi}{\partial t} \right]
\end{aligned} \tag{C.3}$$

## B. Dinamika Medan Magnet

### 4. Komponen radial

Untuk dinamika medan magnet komponen radial, persamaan (C.2) dan (C.3) disubstitusikan ke persamaan (A.44), yaitu

$$\begin{aligned}
e^{\Lambda(r)}r^2 \sin \theta \frac{\partial B^r}{\partial t} &= e^{\phi(r)}(E_\varphi)_{,\theta} - e^{\phi(r)}(E_\theta)_{,\varphi} \\
e^{\Lambda(r)}r^2 \sin \theta \frac{\partial B^r}{\partial t} &= e^{\phi(r)} \left( \frac{1}{4\pi e^{[\phi+\Lambda](r)}r^2 \sin \theta \sigma} \left[ e^{\phi(r)}(B_{r,\theta} - B_{\theta,r}) \right. \right. \\
&\quad \left. \left. - e^{\Lambda(r)}r^2 \sin \theta \frac{\partial E^\varphi}{\partial t} \right] \right)_{,\theta} \\
&\quad - e^{\phi(r)} \left( \frac{1}{4\pi e^{[\phi+\Lambda](r)}r^2 \sin \theta \sigma} \left[ e^{\phi(r)}(B_{\varphi,r} - B_{r,\varphi}) \right. \right. \\
&\quad \left. \left. - e^{\Lambda(r)}r^2 \sin \theta \frac{\partial E^\theta}{\partial t} \right] \right)_{,\varphi}
\end{aligned}$$

sehingga

$$\begin{aligned}
\frac{\partial B^r}{\partial t} = \frac{1}{e^{\Lambda(r)} r^2 \sin \theta} & \left\{ e^{\phi(r)} \left( \frac{1}{4\pi e^{[\phi+\Lambda](r)} r^2 \sin \theta \sigma} \left[ e^{\phi(r)} (B_{r,\theta} - B_{\theta,r}) \right. \right. \right. \\
& \left. \left. \left. - e^{\Lambda(r)} r^2 \sin \theta \frac{\partial E^\varphi}{\partial t} \right] \right)_{,\theta} \right. \\
& \left. - e^{\phi(r)} \left( \frac{1}{4\pi e^{[\phi+\Lambda](r)} r^2 \sin \theta \sigma} \left[ e^{\phi(r)} (B_{\varphi,r} - B_{r,\varphi}) \right. \right. \right. \\
& \left. \left. \left. - e^{\Lambda(r)} r^2 \sin \theta \frac{\partial E^\theta}{\partial t} \right] \right)_{,\varphi} \right\}
\end{aligned}
\tag{C.4}$$

### 5. Komponen polar

Untuk dinamika medan magnet komponen polar, persamaan (C.1) dan (C.3) disubstitusikan ke persamaan (A.43), yaitu

$$\begin{aligned}
e^{\Lambda(r)} r^2 \sin \theta \frac{\partial B^\theta}{\partial t} &= (e^{\phi(r)} E_\varphi)_{,r} - e^{\phi(r)} (E_r)_{,\varphi} \\
e^{\Lambda(r)} r^2 \sin \theta \frac{\partial B^\theta}{\partial t} &= \left( \frac{e^{\phi(r)}}{4\pi e^{[\phi+\Lambda](r)} r^2 \sin \theta \sigma} \left[ e^{\phi(r)} (B_{r,\theta} - B_{\theta,r}) \right. \right. \\
& \left. \left. - e^{\Lambda(r)} r^2 \sin \theta \frac{\partial E^\varphi}{\partial t} \right] \right)_{,r} - e^{\phi(r)} \left( \frac{1}{4\pi e^{[\phi+\Lambda](r)} r^2 \sin \theta \sigma} \left[ e^{\phi(r)} (B_{\theta,\varphi} \right. \right. \\
& \left. \left. - B_{\varphi,\theta}) - e^{\Lambda(r)} r^2 \sin \theta \frac{\partial E^r}{\partial t} \right] \right)_{,\varphi}
\end{aligned}$$

sehingga

$$\begin{aligned}
\frac{\partial B^\theta}{\partial t} = \frac{1}{e^{\Lambda(r)} r^2 \sin \theta} & \left\{ \left( \frac{e^{\phi(r)}}{4\pi e^{[\phi+\Lambda](r)} r^2 \sin \theta \sigma} \left[ e^{\phi(r)} (B_{r,\theta} - B_{\theta,r}) \right. \right. \right. \\
& \left. \left. \left. - e^{\Lambda(r)} r^2 \sin \theta \frac{\partial E^\varphi}{\partial t} \right] \right)_{,r} - e^{\phi(r)} \left( \frac{1}{4\pi e^{[\phi+\Lambda](r)} r^2 \sin \theta \sigma} \left[ e^{\phi(r)} (B_{\theta,\varphi} \right. \right. \right. \\
& \left. \left. \left. - B_{\varphi,\theta}) - e^{\Lambda(r)} r^2 \sin \theta \frac{\partial E^r}{\partial t} \right] \right)_{,\varphi} \right\}
\end{aligned}
\tag{C.5}$$

## 6. Komponen toroidal

Untuk dinamika medan magnet komponen toroidal, persamaan (C.1) dan (C.2) disubstitusikan ke persamaan (A.42), yaitu

$$\begin{aligned}
e^{\Lambda(r)} r^2 \sin \theta \frac{\partial B^\varphi}{\partial t} &= (e^{\phi(r)} E_\theta)_{,r} - e^{\phi(r)} (E_r)_{,\theta} \\
e^{\Lambda(r)} r^2 \sin \theta \frac{\partial B^\varphi}{\partial t} &= \left( e^{\phi(r)} \frac{1}{4\pi e^{[\phi+\Lambda](r)} r^2 \sin \theta \sigma} \left[ e^{\phi(r)} (B_{\varphi,r} - B_{r,\varphi}) \right. \right. \\
& \left. \left. - e^{\Lambda(r)} r^2 \sin \theta \frac{\partial E^\theta}{\partial t} \right] \right)_{,r} - e^{\phi(r)} \left( \frac{1}{4\pi e^{[\phi+\Lambda](r)} r^2 \sin \theta \sigma} \left[ e^{\phi(r)} (B_{\theta,\varphi} \right. \right. \\
& \left. \left. - B_{\varphi,\theta}) - e^{\Lambda(r)} r^2 \sin \theta \frac{\partial E^r}{\partial t} \right] \right)_{,\theta}
\end{aligned}$$

sehingga



$$\begin{aligned}
\frac{\partial B^\varphi}{\partial t} = \frac{1}{e^{\Lambda(r)} r^2 \sin \theta} & \left\{ \left( e^{\phi(r)} \frac{1}{4\pi e^{[\phi+\Lambda](r)} r^2 \sin \theta \sigma} \left[ e^{\phi(r)} (B_{\varphi,r} - B_{r,\varphi}) \right. \right. \right. \\
& \left. \left. \left. - e^{\Lambda(r)} r^2 \sin \theta \frac{\partial E^\theta}{\partial t} \right] \right)_{,r} - e^{\phi(r)} \left( \frac{1}{4\pi e^{[\phi+\Lambda](r)} r^2 \sin \theta \sigma} \left[ e^{\phi(r)} (B_{\theta,\varphi} \right. \right. \right. \\
& \left. \left. \left. - B_{\varphi,\theta}) - e^{\Lambda(r)} r^2 \sin \theta \frac{\partial E^r}{\partial t} \right] \right)_{,\theta} \right\}
\end{aligned}$$

(C.6)

**LAMPIRAN D**  
**PENURUNAN PERSAMAAN GEODESIK**

Geodesik adalah lintasan terpendek pada dua titik di sebuah permukaan. Pada koordinat Cartesian, geodesik adalah garis lurus. Pada koordinat lengkung, geodesik adalah garis lengkung.

Di dalam kalkulus variasi (Boas, 1983), prinsip Fermat menyatakan bahwa lintasan cahaya dengan kecepatan  $v$  adalah sedemikian rupa sehingga waktu tempuh dari satu titik ke titik lainnya minimum, atau

$$\Delta t = \int_A^B \frac{dv}{v} = \frac{1}{v} \int_A^B (dx^2 + dy^2)^{1/2} \tag{C.1}$$

atau

$$\Delta t \cdot v = \int ds = I. \tag{C.2}$$

Syarat agar  $I$  bernilai ekstrem (maksimum atau minimum) harus divariasikan, yakni

$$\delta I = 0 \tag{C.3}$$

sehingga

$$\delta I = \delta \int ds = 0. \tag{C.4}$$

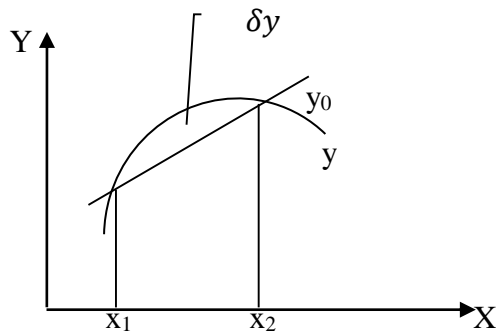
Sementara itu, diberikan elemen garis dari ruang yang hendak kita tinjau adalah

$$ds^2 = g_{\mu\vartheta} dq^\mu dq^\vartheta. \tag{C.5}$$

Variasi  $ds^2$  adalah  $\delta ds^2$  atau  $\delta(ds \cdot ds)$ . Sebelum menghitungnya, kita andaikan sebuah fungsi  $\{x, y(x), y'(x)\}$  atau  $F(x, y', y'')$ , di mana  $x$  tetap. Kita translasikan fungsi tersebut, sehingga

$$\Delta F = F(x, y + \epsilon\mu, y' + \epsilon\mu') - F(x, y, y'). \tag{C.6}$$

Selanjutnya kita definisikan  $Y = y(x) + \epsilon\mu(x)$  atau  $Y = y(x) + \delta y$  atau  $Y = y(x) + (y - y_0)$ . Lalu  $Y' = y'(x) + \epsilon\mu'(x)$  atau  $Y' = y'(x) + \delta dy'$  atau  $Y' = y'(x) + (dy' - dy')$ . Ide ini berasal dari Euler ketika memandang Gambar 2.3.



Gambar 2.3. Koordinat variasi Euler

Pada grafik  $y = y(x)$  ini, jika  $y = y_0$ , akan memenuhi nilai ekstrem baik di  $x_1$  maupun  $x_2$  atau  $\delta y = 0$ . Pada  $x$  tetap, maka  $Y = y(x) + \epsilon\mu(x) = y(x)$  dan  $Y' = y'(x) + \epsilon\mu'(x) = y'(x)$  (Soedjojo, 1995). Kita gunakan deret Taylor untuk  $x = a$ ,  $y = b$  dan  $y' = c$  (Boas, 1983).

$$\begin{aligned}
 F(x, y + \epsilon\mu, y' + \epsilon\mu') &= F(a, b, c) + \frac{dF(a, b, c)}{dx}(x - a) + \frac{dF(a, b, c)}{dy}(y - b) + \frac{dF(a, b, c)}{dy'}(y' - c) + \dots \\
 &= F(a, b, c) + 0 + \frac{dF(a, b, c)}{dy}(y - y + \epsilon\mu) + \frac{dF(a, b, c)}{dy'}(y' - y' + \epsilon\mu') + \dots \\
 &= F(a, b, c) + \frac{dF(a, b, c)}{dy}\epsilon\mu + \frac{dF(a, b, c)}{dy'}\epsilon\mu' + \dots
 \end{aligned}
 \tag{C.7}$$

sehingga

$$\begin{aligned}
 \Delta F &= F(x, y + \epsilon\mu, y' + \epsilon\mu') - F(x, y, y') \\
 &= F(a, b, c) + \frac{dF(a, b, c)}{dy}\epsilon\mu + \frac{dF(a, b, c)}{dy'}\epsilon\mu' - F(x, y, y') \\
 &= \frac{dF(a, b, c)}{dy}\epsilon\mu + \frac{dF(a, b, c)}{dy'}\epsilon\mu' \\
 &= \frac{\partial F}{\partial y}\epsilon\mu + \frac{\partial F}{\partial y'}\epsilon\mu'.
 \end{aligned}
 \tag{C.8}$$

Ini disebut variasi  $F$  atau

$$\delta F = \frac{\partial F}{\partial y}\epsilon\mu + \frac{\partial F}{\partial y'}\epsilon\mu'.
 \tag{C.9}$$

Kita tahu bahwa  $\epsilon\mu = \delta y$ , maka variasi  $F$  dapat ditulis

$$\delta F = \frac{\partial F}{\partial y} \delta y + \frac{\partial F}{\partial y'} \delta y'. \quad (\text{C.10})$$

Dengan demikian, variasi  $ds^2$  dapat diperoleh

$$\begin{aligned} \delta(ds \cdot ds) &= \frac{\partial(ds \cdot ds)}{\partial y} \delta y + \frac{\partial(ds \cdot ds)}{\partial y'} \delta y' \\ &= \left( ds \frac{\partial ds}{\partial y} + ds \frac{\partial ds}{\partial y} \right) \delta y + \left( ds \frac{\partial ds}{\partial y'} + ds \frac{\partial ds}{\partial y'} \right) \delta y' \\ &= ds \left( \frac{\partial ds}{\partial y} \delta y + \frac{\partial ds}{\partial y} \delta y \right) + ds \left( \frac{\partial ds}{\partial y'} \delta y' + \frac{\partial ds}{\partial y'} \delta y' \right) = ds\delta s + ds\delta s \\ &= 2ds\delta s. \end{aligned} \quad (\text{C.11})$$

Oleh karena itu, variasi  $ds^2$  adalah

$$2ds\delta ds = \delta g_{\mu\nu} dq^\mu dq^\nu + g_{\mu\nu} \delta dq^\mu dq^\nu + g_{\mu\nu} dq^\mu \delta dq^\nu. \quad (\text{C.12})$$

Tetapi kita tahu bahwa sifat  $\delta$  sama dengan sifat  $d$  dalam kalkulus dan di depan sudah diketahui bahwa

$$\delta dy = dy - dy_0 = dy' - dy \quad (\text{C.13})$$

atau dengan koordinat umum

$$\delta dq = dq' - dq.$$

(C.14)

Dari kurva di atas, kita dapatkan  $\delta y = y - y_0$ . Ini juga berlaku untuk  $\delta x = x - x_0$ . Jika kita pakai koordinat umum, maka  $\delta q = q - q_0 = q' - q$  atau  $q' = q + \delta q$ . Masukkan hasil ini, maka

$$\delta dq = dq' - dq = d(q + \delta q) - dq = d\delta q. \quad (C.15)$$

Sehingga variasi  $ds^2$  dapat ditulis

$$2ds\delta ds = \delta g_{\mu\nu} dq^\mu dq^\nu + g_{\mu\nu} d\delta q^\mu dq^\nu + g_{\mu\nu} dq^\mu d\delta q^\nu. \quad (C.16)$$

Jika persamaan ini dibagi  $2ds \cdot ds$  lalu dikalikan  $ds$  dan diintegrasikan, maka akan kita dapatkan

$$\delta \int ds = \frac{1}{2} \int \{ \delta g_{\mu\nu} dq^\mu dq^\nu + g_{\mu\nu} d\delta q^\mu dq^\nu + g_{\mu\nu} dq^\mu d\delta q^\nu \} ds = 0. \quad (C.17)$$

Dari persamaan (2.74), maka memberikan

$$\frac{1}{2} \int \left\{ \delta g_{\mu\nu} \frac{dq^\mu}{ds} \frac{dq^\nu}{ds} + g_{\mu\nu} \frac{d\delta q^\mu}{ds} \frac{dq^\nu}{ds} + g_{\mu\nu} \frac{dq^\mu}{ds} \frac{d\delta q^\nu}{ds} \right\} ds = 0. \quad (C.18)$$

Dengan menggunakan hubungan

$$\delta g_{\mu\vartheta} = \frac{\partial g_{\mu\vartheta}}{\partial q^\gamma} \delta q^\gamma \quad (\text{C.19})$$

dan

$$\begin{aligned} & \frac{d}{ds} \left( g_{\mu\vartheta} \delta q^\mu \frac{dq^\vartheta}{ds} \right) - \frac{d}{ds} \left( g_{\mu\vartheta} \frac{dq^\vartheta}{ds} \right) \delta q^\mu \\ &= \frac{dg_{\mu\vartheta}}{ds} \delta q^\mu \frac{dq^\vartheta}{ds} + g_{\mu\vartheta} \frac{d\delta q^\mu}{ds} \frac{dq^\vartheta}{ds} + g_{\mu\vartheta} \delta q^\mu \frac{d^2 q^\vartheta}{ds^2} - \frac{dg_{\mu\vartheta}}{ds} \delta q^\mu \frac{dq^\vartheta}{ds} \\ &+ g_{\mu\vartheta} \delta q^\mu \frac{d^2 q^\vartheta}{ds^2} = g_{\mu\vartheta} \frac{d\delta q^\mu}{ds} \frac{dq^\vartheta}{ds}. \end{aligned} \quad (\text{C.20})$$

Maka persamaan (2.76) menjadi

$$\frac{1}{2} \int \left\{ \frac{\partial g_{\mu\vartheta}}{\partial q^\gamma} \delta q^\gamma \frac{dq^\mu}{ds} \frac{dq^\vartheta}{ds} - \frac{d}{ds} \left( g_{\mu\vartheta} \frac{dq^\vartheta}{ds} \right) \delta q^\mu - \frac{d}{ds} \left( g_{\mu\vartheta} \frac{dq^\vartheta}{ds} \right) \delta q^\vartheta \right\} ds = 0 \quad (\text{C.21})$$

atau

$$\begin{aligned} & \frac{1}{2} \int \left\{ \frac{\partial g_{\mu\vartheta}}{\partial q^\gamma} \delta q^\gamma \frac{dq^\mu}{ds} \frac{dq^\vartheta}{ds} - \frac{d}{ds} \left( g_{\gamma\vartheta} \frac{dq^\vartheta}{ds} + g_{\mu\gamma} \frac{dq^\mu}{ds} \right) \delta q^\gamma \right\} ds \\ &= \frac{1}{2} \int \left\{ \frac{\partial g_{\mu\vartheta}}{\partial q^\gamma} \frac{dq^\mu}{ds} \frac{dq^\vartheta}{ds} - \frac{d}{ds} \left( g_{\gamma\vartheta} \frac{dq^\vartheta}{ds} + g_{\mu\gamma} \frac{dq^\mu}{ds} \right) \right\} \delta q^\gamma ds = 0. \end{aligned} \quad (\text{C.22})$$

$\delta q^\gamma$  secara umum tidak sama dengan nol, sehingga integrannya harus sama dengan nol. Kita dapat menunjukkan hal ini dengan metode kontradiksi begini: andaikan integrannya tidak sama dengan nol, maka integrannya  $>0$  atau  $<0$ , sehingga ruas kiri akan positif, dan ini bertentangan dengan kenyataan bahwa  $\delta \int ds = 0$ . Jadi integrannya harus sama dengan nol

$$\frac{\partial g_{\mu\vartheta}}{\partial q^\gamma} \frac{dq^\mu}{ds} \frac{dq^\vartheta}{ds} - \frac{d}{ds} \left( g_{\gamma\vartheta} \frac{dq^\vartheta}{ds} + g_{\mu\gamma} \frac{dq^\mu}{ds} \right) = 0. \quad (\text{C.23})$$

Ini disebut persamaan geodesik. Untuk menghubungkan persamaan geodesik dengan Simbol Christoffel, gunakan hubungan

$$\frac{dg_{\mu\gamma}}{ds} = \frac{\partial g_{\mu\gamma}}{\partial q^\gamma} \frac{dq^\gamma}{ds} \quad \text{dan} \quad \frac{dg_{\gamma\vartheta}}{ds} = \frac{\partial g_{\gamma\vartheta}}{\partial q^\mu} \frac{dq^\mu}{ds} \quad (\text{C.24})$$

sehingga memberikan

$$\begin{aligned} & \frac{\partial g_{\mu\vartheta}}{\partial q^\gamma} \frac{dq^\mu}{ds} \frac{dq^\vartheta}{ds} - \frac{dg_{\gamma\vartheta}}{ds} \frac{dq^\vartheta}{ds} - g_{\gamma\vartheta} \frac{d^2 q^\vartheta}{ds^2} - \frac{dg_{\mu\gamma}}{ds} \frac{dq^\mu}{ds} - g_{\mu\gamma} \frac{d^2 q^\mu}{ds^2} = 0 \\ & \frac{\partial g_{\mu\vartheta}}{\partial q^\gamma} \frac{dq^\mu}{ds} \frac{dq^\vartheta}{ds} - \frac{dg_{\gamma\vartheta}}{ds} \frac{dq^\mu}{ds} \frac{dq^\vartheta}{ds} - g_{\gamma\vartheta} \frac{d^2 q^\vartheta}{ds^2} - \frac{dg_{\mu\gamma}}{dq^\vartheta} \frac{dq^\vartheta}{ds} \frac{dq^\mu}{ds} - g_{\mu\gamma} \frac{d^2 q^\mu}{ds^2} = 0 \\ & \left( \frac{\partial g_{\mu\vartheta}}{\partial q^\gamma} - \frac{dg_{\mu\gamma}}{dq^\vartheta} - \frac{dg_{\gamma\vartheta}}{dq^\mu} \right) \frac{dq^\mu}{ds} \frac{dq^\vartheta}{ds} - g_{\gamma\vartheta} \frac{d^2 q^\vartheta}{ds^2} - g_{\mu\gamma} \frac{d^2 q^\mu}{ds^2} = 0 \\ & \left( \frac{\partial g_{\mu\vartheta}}{\partial q^\gamma} - \frac{dg_{\mu\gamma}}{dq^\vartheta} - \frac{dg_{\gamma\vartheta}}{dq^\mu} \right) \frac{dq^\mu}{ds} \frac{dq^\vartheta}{ds} = 2g_{\mu\gamma} \frac{d^2 q^\mu}{ds^2}. \end{aligned} \quad (\text{C.25})$$



Kalikan dengan  $g^{\gamma\sigma}$ , sehingga

$$\begin{aligned} g^{\gamma\sigma} \left( \frac{\partial g_{\mu\vartheta}}{\partial q^\gamma} - \frac{dg_{\mu\gamma}}{dq^\vartheta} - \frac{dg_{\gamma\vartheta}}{dq^\mu} \right) \frac{dq^\mu}{ds} \frac{dq^\vartheta}{ds} &= 2g^{\gamma\sigma} g_{\mu\gamma} \frac{d^2 q^\mu}{ds^2} = 2g_\mu^\sigma \frac{d^2 q^\mu}{ds^2} = 2g_\sigma^\sigma \frac{d^2 q^\sigma}{ds^2} \\ &= 2 \frac{d^2 q^\sigma}{ds^2} \end{aligned}$$

atau

$$\frac{g^{\gamma\sigma}}{2} \left( \frac{\partial g_{\mu\vartheta}}{\partial q^\gamma} - \frac{dg_{\mu\gamma}}{dq^\vartheta} - \frac{dg_{\gamma\vartheta}}{dq^\mu} \right) \frac{dq^\mu}{ds} \frac{dq^\vartheta}{ds} - \frac{d^2 q^\sigma}{ds^2} = 0. \quad (\text{C.26})$$

Dengan menggunakan Simbol Christoffel, maka

$$\Gamma_{\mu\vartheta}^\sigma \frac{dq^\mu}{ds} \frac{dq^\vartheta}{ds} - \frac{d^2 q^\sigma}{ds^2} = 0. \quad (\text{C.27})$$

Ini adalah persamaan geodesik di mana Simbol Christoffel menjadi koefisien kecepatan (Purwanto, 2009).

**LAMPIRAN E**  
**PENURUNAN RUANG-WAKTU SCHWARZSCHILD**

Diberikan sebuah elemen garis

$$ds^2 = dr^2 + r^2(d\theta^2 + \sin^2\theta d\varphi^2). \tag{D.1}$$

Ini adalah elemen garis koordinat bola tak bergantung waktu. Sedangkan elemen garis koordinat bola bergantung waktu adalah

$$ds^2 = c^2 dt^2 - \{dr^2 + r^2(d\theta^2 + \sin^2\theta d\varphi^2)\}. \tag{D.2}$$

Ruang-waktu ini disebut sebagai ruang waktu Minkowski, dengan metrik  $g_{00} = c^2$ ,  $g_{11} = -1$ ,  $g_{22} = -r^2$ ,  $g_{33} = -r^2 \sin^2\theta$ . Ruang-waktu ini terbentuk dengan distribusi massa tidak ada ( $M = 0$ ), sehingga bentuk ruang-waktunya datar. Jika ada distribusi massa ( $M \neq 0$ ), maka ruang menjadi melengkung. Oleh karena itu, kita perlu memperumum ruang-waktu pada koordinat simetri bola. Ruang-waktu tersebut berbentuk

$$ds^2 = e^v dt^2 - e^\lambda dr^2 - r^2(d\theta^2 + \sin^2\theta d\varphi^2) \tag{D.3}$$

dengan  $v = v(r)$ ,  $\lambda = \lambda(r)$  dan tensor metriknya

$$\begin{aligned}
g_{\mu\nu} &= \begin{pmatrix} e^v & 0 & 0 & 0 \\ 0 & -e^\lambda & 0 & 0 \\ 0 & 0 & -r^2 & 0 \\ 0 & 0 & 0 & -r^2 \sin^2 \theta \end{pmatrix} \\
g^{\mu\nu} &= \begin{pmatrix} e^{-v} & 0 & 0 & 0 \\ 0 & -e^{-\lambda} & 0 & 0 \\ 0 & 0 & -r^{-2} & 0 \\ 0 & 0 & 0 & -r^{-2} \sin^{-2} \theta \end{pmatrix}.
\end{aligned}
\tag{D.4}$$

Determinannya adalah

$$\begin{aligned}
\det g_{\mu\nu} = g &= \begin{pmatrix} e^v & 0 & 0 & 0 \\ 0 & -e^\lambda & 0 & 0 \\ 0 & 0 & -r^2 & 0 \\ 0 & 0 & 0 & -r^2 \sin^2 \theta \end{pmatrix} \\
&= (e^v \cdot [-e^\lambda] \cdot [-r^2] \cdot [-r^2 \sin^2 \theta] + 0 + 0 + 0) - (0 + 0 + 0 + 0) = -e^{v+\lambda} r^4 \sin^2 \theta.
\end{aligned}
\tag{D.5}$$

Untuk menentukan nilai  $e^v$  dan  $e^\lambda$ , kita mesti menentukan semua komponen Simbol Christoffel dan tensor kurvatur Ricci. Adapun komponen Simbol Christoffelnya adalah sebagai berikut

$$\Gamma_{\mu\nu}^\alpha = \frac{g^{\alpha\beta}}{2} \left\{ \frac{\partial g_{\nu\beta}}{\partial q^\mu} + \frac{\partial g_{\alpha\mu}}{\partial q^\nu} - \frac{\partial g_{\mu\nu}}{\partial q^\beta} \right\} = \frac{g^{\alpha\beta}}{2} \{ \partial_\mu g_{\nu\beta} + \partial_\nu g_{\alpha\mu} - \partial_\beta g_{\mu\nu} \}
\tag{D.6}$$

(Hidayat, 2010).

1. Untuk  $\mu = \nu = \alpha$

$$\Gamma_{\mu\mu}^\mu = \frac{g^{\mu\beta}}{2} \{ \partial_\mu g_{\mu\beta} + \partial_\mu g_{\mu\mu} - \partial_\beta g_{\mu\mu} \}.$$

Tetapi dalam kasus ini, karena komponen tensor metrik non-diagonalnya bernilai nol ( $g^{\mu\beta} = 0$ ), sehingga komponen tensor metrik yang ada harganya hanya yang diagonal saja ( $g^{\mu\mu} \neq 0$ ), maka

$$\Gamma_{\mu\mu}^{\mu} = \frac{g^{\mu\mu}}{2} \{ \partial_{\mu} g_{\mu\mu} + \partial_{\mu} g_{\mu\mu} - \partial_{\mu} g_{\mu\mu} \} = \frac{g^{\mu\mu}}{2} \partial_{\mu} g_{\mu\mu} = \frac{1}{2g_{\mu\mu}} \partial_{\mu} g_{\mu\mu}.$$

Dari  $\int \frac{du}{u} = \ln|u| + C$ , maka

$$\Gamma_{\mu\mu}^{\mu} = \frac{1}{2} \frac{\partial_{\mu} g_{\mu\mu}}{g_{\mu\mu}} = \frac{1}{2} \partial_{\mu} \left( \int \frac{\partial_{\mu} g_{\mu\mu}}{g_{\mu\mu}} \right) = \frac{1}{2} \partial_{\mu} \ln g_{\mu\mu}.$$

Maka untuk  $\Gamma_{00}^0$  adalah

$$\Gamma_{00}^0 = \frac{1}{2} \partial_0 \ln g_{00} = \frac{1}{2} \frac{\partial}{\partial t} \ln e^v.$$

Dari  $\ln(e^y) = y$ , maka

$$\Gamma_{00}^0 = \frac{1}{2} \frac{\partial v(r)}{\partial t} = 0.$$

Untuk  $\Gamma_{11}^1$  adalah

$$\Gamma_{11}^1 = \frac{1}{2} \partial_1 \ln g_{11} = \frac{1}{2} \frac{\partial}{\partial r} \ln e^{\lambda} = \frac{1}{2} \frac{\partial \lambda(r)}{\partial r} = 0.$$

Untuk  $\Gamma_{22}^2$  dan mengingat  $\frac{d}{dx} \ln x = \frac{1}{x}$  adalah

$$\Gamma_{22}^2 = \frac{1}{2} \partial_2 \ln g_{22} = \frac{1}{2} \frac{\partial}{\partial \theta} \ln r^2 = 0.$$

Untuk  $\Gamma_{33}^3$

$$\Gamma_{33}^3 = \frac{1}{2} \partial_3 \ln g_{33} = \frac{1}{2} \frac{\partial}{\partial \varphi} (r^2 \sin^2 \theta) = 0.$$

2. Untuk  $\mu = \nu \neq \alpha$  di mana  $\beta = \alpha$

$$\Gamma_{\mu\mu}^\alpha = \frac{g^{\alpha\alpha}}{2} \{ \partial_\mu g_{\mu\alpha} + \partial_\mu g_{\alpha\mu} - \partial_\alpha g_{\mu\mu} \} = \frac{g^{\alpha\alpha}}{2} \{ 2\partial_\mu g_{\mu\alpha} - \partial_\alpha g_{\mu\mu} \}.$$

Karena  $\mu \neq \alpha$ , sedangkan kita mencari metrik diagonalnya, maka  $2\partial_\mu g_{\mu\alpha} = 2\partial_\mu 0 = 0$ . Sehingga

$$\Gamma_{\mu\mu}^\alpha = -\frac{g^{\alpha\alpha}}{2} \partial_\alpha g_{\mu\mu}.$$

Untuk  $\Gamma_{11}^0$

$$\Gamma_{11}^0 = -\frac{g^{00}}{2} \partial_0 g_{11} = -\frac{1}{2} e^{-\nu} \frac{\partial}{\partial t} (-e^{-\lambda}) = 0.$$

Untuk  $\Gamma_{22}^0$

$$\Gamma_{22}^0 = -\frac{g^{00}}{2} \partial_0 g_{22} = -\frac{1}{2} e^{-\lambda} \frac{\partial}{\partial t} (-r^2) = 0.$$

Untuk  $\Gamma_{33}^0$

$$\Gamma_{33}^0 = -\frac{g^{00}}{2} \partial_0 g_{33} = -\frac{1}{2} e^{-\lambda} \frac{\partial}{\partial t} (-r^2 \sin^2 \theta) = 0.$$

Untuk  $\Gamma_{00}^1$  dan mengingat  $\frac{de^u}{dx} = e^u \frac{du}{dx}$

$$\Gamma_{00}^1 = -\frac{g^{11}}{2} \partial_1 g_{00} = \frac{e^{-\lambda} \partial e^v}{2 \partial r} = \frac{e^{-\lambda}}{2} e^v \frac{\partial v}{\partial r} = \frac{1}{2} (e^{-\lambda} e^v) v' = \frac{v'}{2} e^{-\lambda+v}.$$

Untuk  $\Gamma_{11}^1$

$$\Gamma_{11}^1 = -\frac{g^{11}}{2} \partial_1 g_{11} = \frac{e^{-\lambda} \partial(e^{-\lambda})}{2 \partial r} = \frac{e^{-\lambda}}{2} e^{-\lambda} \frac{\partial \lambda}{\partial r} = \frac{1}{2} \frac{\partial \lambda}{\partial r}.$$

Untuk  $\Gamma_{22}^1$

$$\Gamma_{22}^1 = -\frac{g^{11}}{2} \partial_1 g_{22} = \frac{e^{-\lambda} \partial(r^2)}{2 \partial r} = \frac{e^{-\lambda} \partial r^2}{2 \partial r} = r e^{-\lambda}.$$

Untuk  $\Gamma_{33}^1$

$$\begin{aligned} \Gamma_{33}^1 &= -\frac{g^{11}}{2} \partial_1 g_{33} = \frac{e^{-\lambda} \partial(r^2 \sin^2 \theta)}{2 \partial r} = \frac{e^{-\lambda}}{2} \left( \frac{\partial r^2}{\partial r} \sin^2 \theta + r^2 \frac{\partial \sin^2 \theta}{\partial r} \right) \\ &= \frac{e^{-\lambda}}{2} (2r \sin^2 \theta + 0) = r \sin^2 \theta e^{-\lambda}. \end{aligned}$$

Untuk  $\Gamma_{00}^2$

$$\Gamma_{00}^2 = -\frac{g^{22}}{2} \partial_2 g_{00} = \frac{(r^{-2}) \partial e^v}{2 \partial \theta} = 0.$$

Untuk  $\Gamma_{11}^2$

$$\Gamma_{11}^2 = -\frac{g^{22}}{2} \partial_2 g_{11} = \frac{(r^{-2})}{2} \frac{\partial e^\lambda}{\partial \theta} = 0.$$

Untuk  $\Gamma_{22}^2$

$$\Gamma_{22}^2 = -\frac{g^{22}}{2} \partial_2 g_{22} = \frac{(r^{-2})}{2} \frac{\partial r^{-2}}{\partial \theta} = 0.$$

Untuk  $\Gamma_{33}^2$

$$\begin{aligned} \Gamma_{33}^2 &= -\frac{g^{22}}{2} \partial_2 g_{33} = \frac{(r^{-2})}{2} \frac{\partial (r^2 \sin^2 \theta)}{\partial \theta} = \frac{1}{2r^2} \left( \frac{\partial r^2}{\partial \theta} \sin^2 \theta + r^2 \frac{\partial \sin^2 \theta}{\partial \theta} \right) \\ &= \frac{1}{2r^2} \left( 0 + r^2 \frac{\partial \sin^2 \theta}{\partial \theta} \right) = \frac{1}{2} \frac{\partial \sin^2 \theta}{\partial \theta}. \end{aligned}$$

Misalkan  $y = u^2$  dengan  $u = \sin \theta$ , maka  $\frac{dy}{du} = 2u$  dan  $\frac{du}{d\theta} = \cos \theta$ , sehingga  $\frac{dy}{d\theta} = \frac{dy}{du} \frac{du}{d\theta} = 2u \cos \theta = 2 \sin \theta \cos \theta$ . Dengan begitu

$$\Gamma_{33}^2 = \frac{1}{2} 2 \sin \theta \cos \theta = \sin \theta \cos \theta.$$

Untuk  $\Gamma_{00}^3$

$$\Gamma_{00}^3 = -\frac{g^{33}}{2} \partial_3 g_{00} = \frac{(r^{-2})}{2} \sin^2 \theta \frac{\partial (e^v)}{\partial \varphi} = 0.$$

Komponen  $\Gamma_{11}^3 = \Gamma_{22}^3 = \Gamma_{33}^3 = \Gamma_{00}^3 = 0$ , karena  $g_{\mu\mu}$  bukan fungsi  $\varphi$ .

3. Untuk  $v = \alpha \neq \mu$  di mana  $\beta = v$

$$\begin{aligned}\Gamma_{\mu v}^v &= \frac{g^{vv}}{2} \{ \partial_\mu g_{vv} + \partial_v g_{\alpha\mu} - \partial_v g_{\mu v} \} = \frac{g^{vv}}{2} \partial_\mu g_{vv} = \frac{1}{2} \frac{\partial_\mu g^{vv}}{g_{vv}} \\ &= \frac{1}{2} \partial_\mu \left( \int \frac{\partial_\mu g^{vv}}{g_{vv}} \right) = \frac{1}{2} \partial_\mu \ln g_{vv}.\end{aligned}$$

Untuk  $\Gamma_{10}^0$  dan mengingat  $\ln(e^v) = y$

$$\Gamma_{10}^0 = \frac{1}{2} \partial_1 \ln g_{00} = \frac{1}{2} \frac{\partial(\ln e^v)}{\partial r} = \frac{1}{2} \frac{\partial v}{\partial r} = \frac{v'}{2}.$$

Untuk  $\Gamma_{20}^0$

$$\Gamma_{20}^0 = \frac{1}{2} \partial_2 \ln g_{00} = \frac{1}{2} \frac{\partial(\ln e^v)}{\partial \theta} = 0.$$

Untuk  $\Gamma_{30}^0$

$$\Gamma_{30}^0 = \frac{1}{2} \partial_3 \ln g_{00} = \frac{1}{2} \frac{\partial(\ln e^v)}{\partial \varphi} = 0.$$

Untuk  $\Gamma_{01}^1$

$$\Gamma_{01}^1 = \frac{1}{2} \partial_0 \ln g_{11} = \frac{1}{2} \frac{\partial(\ln -e^\lambda)}{\partial t} = 0.$$

Dengan cara yang sama,  $\Gamma_{21}^1 = \Gamma_{31}^1 = 0$ .



Untuk  $\Gamma_{02}^2$

$$\Gamma_{02}^2 = \frac{1}{2} \partial_0 \ln g_{22} = \frac{1}{2} \frac{\partial(\ln -r^2)}{\partial t} = 0.$$

Untuk  $\Gamma_{12}^2$  serta mengingat  $u = r^2$  dan  $\frac{d}{dx} \ln u = \frac{1}{u} \frac{d}{dx} u$

$$\Gamma_{12}^2 = \frac{1}{2} \partial_1 \ln g_{22} = \frac{1}{2} \frac{\partial(\ln -r^2)}{\partial r} = \frac{1}{2} \frac{1}{r^2} \frac{\partial r^2}{\partial r} = \frac{2}{2} \frac{r}{r^2} = \frac{1}{r}.$$

Untuk  $\Gamma_{32}^2$

$$\Gamma_{32}^2 = \frac{1}{2} \partial_3 \ln g_{22} = \frac{1}{2} \frac{\partial(\ln -r^2)}{\partial \varphi} = 0.$$

Untuk  $\Gamma_{03}^3$

$$\Gamma_{03}^3 = \frac{1}{2} \partial_0 \ln g_{33} = \frac{1}{2} \frac{\partial(\ln r^2 \sin^2 \theta)}{\partial t} = 0.$$

Untuk  $\Gamma_{13}^3$

$$\begin{aligned} \Gamma_{13}^3 &= \frac{1}{2} \partial_1 \ln g_{33} = \frac{1}{2} \frac{\partial(\ln r^2 \sin^2 \theta)}{\partial r} = \frac{1}{2} \left( \frac{\partial}{\partial r} \ln r^2 + \frac{\partial}{\partial r} \ln \sin^2 \theta \right) \\ &= \frac{1}{r} + 0 = \frac{1}{r}. \end{aligned}$$

Untuk  $\Gamma_{23}^3$

$$\Gamma_{23}^3 = \frac{1}{2} \partial_2 \ln g_{33} = \frac{1}{2} \frac{\partial(\ln r^2 + \ln \sin^2 \theta)}{\partial \theta} = \frac{1}{2} \frac{\partial(\ln \sin^2 \theta)}{\partial \theta}$$

dengan memisalkan  $y = u^2$  dan  $u = \sin^2 \theta$ , maka  $\frac{dy}{du} = 2u$ ,  $\frac{du}{d\theta} = \cos \theta$ , serta  $\frac{dy}{du} \frac{du}{d\theta} = 2 \sin \theta \cos \theta$ , sehingga

$$\begin{aligned} \Gamma_{23}^3 &= \frac{1}{2} \frac{\partial(\ln u^2)}{\partial \theta} = \frac{1}{2} \frac{1}{u^2} \frac{du^2}{d\theta} = \frac{1}{2} \frac{1}{\sin^2 \theta} \frac{d}{d\theta} \sin^2 \theta = \frac{1}{2} \frac{1}{\sin^2 \theta} 2 \sin \theta \cos \theta = \frac{\cos \theta}{\sin \theta} \\ &= \cot \theta. \end{aligned}$$

4. Untuk  $\mu \neq \nu \neq \alpha$  di mana  $\beta = \alpha$

$$\Gamma_{\mu\nu}^\alpha = \frac{g^{\alpha\alpha}}{2} \{ \partial_\mu g_{\nu\alpha} + \partial_\nu g_{\alpha\mu} - \partial_\alpha g_{\mu\nu} \} = 0.$$

Jadi, ada 9 komponen Simbol Christoffel tak nol, yaitu

$$\begin{aligned} \Gamma_{10}^0 &= \frac{v'}{2}, \quad \Gamma_{00}^1 = \frac{v'}{2} e^{-\lambda+v}, \quad \Gamma_{12}^2 = \frac{1}{r}, \quad \Gamma_{13}^3 = \frac{1}{r}, \quad \Gamma_{11}^1 = \frac{1}{2} \frac{\partial \lambda}{\partial r}, \quad \Gamma_{33}^2 = \sin \theta \cos \theta \\ \Gamma_{23}^3 &= \cot \theta, \quad \Gamma_{22}^1 = r e^{-\lambda}, \quad \Gamma_{33}^1 = r \sin^2 \theta e^{-\lambda}. \end{aligned} \tag{D.7}$$

Nilai-nilai tersebut, kita masukkan ke dalam tensor Ricci

$$R_{\mu\vartheta} = \partial_\alpha \Gamma_{\mu\vartheta}^\alpha - \partial_\mu \Gamma_{\alpha\vartheta}^\alpha + \Gamma_{\mu\vartheta}^\beta \Gamma_{\alpha\beta}^\alpha - \Gamma_{\alpha\vartheta}^\beta \Gamma_{\mu\beta}^\alpha. \tag{D.8}$$

Semua suku non-diagonalnya ( $\mu\nu$ ) lenyap, sementara suku diagonalnya ( $\mu\mu$ ) adalah

$$R_{\mu\mu} = \partial_\alpha \Gamma_{\mu\mu}^\alpha - \partial_\mu \Gamma_{\alpha\mu}^\alpha + \Gamma_{\mu\mu}^\beta \Gamma_{\alpha\beta}^\alpha - \Gamma_{\alpha\mu}^\beta \Gamma_{\mu\beta}^\alpha. \quad (\text{D.9})$$

5. Untuk  $R_{00}$

$$\begin{aligned}
R_{00} &= \partial_0 \Gamma_{00}^0 + \partial_1 \Gamma_{00}^1 + \partial_2 \Gamma_{00}^2 + \partial_3 \Gamma_{00}^3 \\
&\quad - \partial_0 \Gamma_{00}^0 - \partial_0 \Gamma_{01}^1 - \partial_0 \Gamma_{02}^2 - \partial_0 \Gamma_{03}^3 \\
&\quad + \Gamma_{00}^0 \Gamma_{00}^0 + \Gamma_{00}^0 \Gamma_{01}^1 + \Gamma_{00}^0 \Gamma_{02}^2 + \Gamma_{00}^0 \Gamma_{03}^3 \\
&\quad + \Gamma_{00}^1 \Gamma_{10}^0 + \Gamma_{00}^1 \Gamma_{11}^1 + \Gamma_{00}^1 \Gamma_{12}^2 + \Gamma_{00}^1 \Gamma_{13}^3 \\
&\quad + \Gamma_{00}^2 \Gamma_{20}^0 + \Gamma_{00}^2 \Gamma_{21}^1 + \Gamma_{00}^2 \Gamma_{22}^2 + \Gamma_{00}^2 \Gamma_{23}^3 \\
&\quad + \Gamma_{00}^3 \Gamma_{30}^0 + \Gamma_{00}^3 \Gamma_{31}^1 + \Gamma_{00}^3 \Gamma_{32}^2 + \Gamma_{00}^3 \Gamma_{33}^3 \\
&\quad - \Gamma_{00}^0 \Gamma_{00}^0 - \Gamma_{01}^0 \Gamma_{00}^1 - \Gamma_{02}^0 \Gamma_{00}^2 - \Gamma_{03}^0 \Gamma_{00}^3 \\
&\quad - \Gamma_{00}^1 \Gamma_{10}^0 - \Gamma_{01}^1 \Gamma_{10}^1 - \Gamma_{02}^1 \Gamma_{10}^2 - \Gamma_{03}^1 \Gamma_{10}^3 \\
&\quad - \Gamma_{00}^2 \Gamma_{20}^0 - \Gamma_{01}^2 \Gamma_{20}^1 - \Gamma_{02}^2 \Gamma_{20}^2 - \Gamma_{03}^2 \Gamma_{20}^3 \\
&\quad - \Gamma_{00}^3 \Gamma_{30}^0 - \Gamma_{01}^3 \Gamma_{30}^1 - \Gamma_{02}^3 \Gamma_{30}^2 - \Gamma_{03}^3 \Gamma_{30}^3 \\
&\quad = 0 + \partial_1 \Gamma_{00}^1 + 0 + 0 \\
&\quad \quad - 0 - 0 - 0 - 0 \\
&\quad \quad + 0 + 0 + 0 + 0 \\
&\quad + \Gamma_{00}^1 \Gamma_{10}^0 + \Gamma_{00}^1 \Gamma_{11}^1 + \Gamma_{00}^1 \Gamma_{12}^2 + \Gamma_{00}^1 \Gamma_{13}^3 \\
&\quad \quad + 0 + 0 + 0 + 0 \\
&\quad \quad + 0 + 0 + 0 + 0 \\
&\quad \quad - 0 - \Gamma_{01}^0 \Gamma_{00}^1 - 0 - 0 \\
&\quad \quad - \Gamma_{00}^1 \Gamma_{10}^0 - 0 - 0 - 0 \\
&\quad \quad - 0 - 0 - 0 - 0 \\
&\quad \quad - 0 - 0 - 0 - 0 \\
&= \partial_1 \Gamma_{00}^1 + \Gamma_{00}^1 (\Gamma_{10}^0 + \Gamma_{11}^1 + \Gamma_{12}^2 + \Gamma_{13}^3) - \Gamma_{01}^0 \Gamma_{00}^1 - \Gamma_{00}^1 \Gamma_{10}^0 \\
&= \frac{\partial}{\partial r} \left( \frac{1}{2} \frac{\partial v}{\partial r} e^{v-\lambda} \right) + \frac{1}{2} \frac{\partial v}{\partial r} e^{v-\lambda} \left( \frac{1}{2} \frac{\partial v}{\partial r} + \frac{1}{2} \frac{\partial \lambda}{\partial r} + \frac{2}{r} \right) - 2 \frac{1}{2} \frac{\partial v}{\partial r} e^{v-\lambda} \frac{1}{2} \frac{\partial v}{\partial r}
\end{aligned}$$

$$= \frac{1}{2} \left( \frac{\partial v'}{\partial r} e^{v-\lambda} + v' \frac{\partial e^{v-\lambda}}{\partial r} \right) + \frac{v'}{2} e^{v-\lambda} \left( \frac{v' + \lambda'}{2} + \frac{2}{r} \right) - \frac{v'^2}{2} e^{v-\lambda}.$$

Mengingat  $\frac{de^u}{dx} = e^u \frac{du}{dx}$ , maka

$$\begin{aligned} R_{00} &= \frac{v''}{2} e^{v-\lambda} + \frac{v'}{2} e^{v-\lambda} \frac{\partial(v-\lambda)}{\partial r} + \frac{v'}{2} e^{v-\lambda} \left( \frac{2}{r} + \frac{v' + \lambda'}{2} \right) - \frac{v'^2}{2} e^{v-\lambda} \\ &= e^{v-\lambda} \left( \frac{v''}{2} + \frac{v'}{2} (v-\lambda) \right) + e^{v-\lambda} \left( \frac{v'}{r} + \frac{v'^2}{4} + \frac{v'\lambda'}{4} \right) - \frac{v'^2}{2} e^{v-\lambda} \\ &= e^{v-\lambda} \left( \frac{v''}{2} + \frac{v'}{r} + \frac{v'^2}{2} - \frac{v'\lambda'}{2} + \frac{v'^2}{4} + \frac{v'\lambda'}{4} - \frac{v'^2}{2} \right) \\ &= e^{v-\lambda} \left\{ \frac{v''}{2} + \frac{v'}{r} - \frac{v'\lambda'}{4} + \frac{v'^2}{4} \right\}. \end{aligned}$$

6. Untuk  $R_{11}$

$$\begin{aligned} R_{11} &= \partial_0 \Gamma_{11}^0 + \partial_1 \Gamma_{11}^1 + \partial_2 \Gamma_{11}^2 + \partial_3 \Gamma_{11}^3 \\ &\quad - \partial_1 \Gamma_{10}^0 - \partial_1 \Gamma_{11}^1 - \partial_1 \Gamma_{12}^2 - \partial_1 \Gamma_{13}^3 \\ &\quad + \Gamma_{11}^0 \Gamma_{00}^0 + \Gamma_{11}^0 \Gamma_{01}^1 + \Gamma_{11}^0 \Gamma_{02}^2 + \Gamma_{11}^0 \Gamma_{03}^3 \\ &\quad + \Gamma_{11}^1 \Gamma_{10}^0 + \Gamma_{11}^1 \Gamma_{11}^1 + \Gamma_{11}^1 \Gamma_{12}^2 + \Gamma_{11}^1 \Gamma_{13}^3 \\ &\quad + \Gamma_{11}^2 \Gamma_{20}^0 + \Gamma_{11}^2 \Gamma_{21}^1 + \Gamma_{11}^2 \Gamma_{22}^2 + \Gamma_{11}^2 \Gamma_{23}^3 \\ &\quad + \Gamma_{11}^3 \Gamma_{30}^0 + \Gamma_{11}^3 \Gamma_{31}^1 + \Gamma_{11}^3 \Gamma_{32}^2 + \Gamma_{11}^3 \Gamma_{33}^3 \\ &\quad - \Gamma_{10}^0 \Gamma_{01}^0 - \Gamma_{11}^0 \Gamma_{01}^1 - \Gamma_{12}^0 \Gamma_{01}^2 - \Gamma_{13}^0 \Gamma_{01}^3 \\ &\quad - \Gamma_{10}^1 \Gamma_{11}^0 - \Gamma_{11}^1 \Gamma_{11}^1 - \Gamma_{12}^1 \Gamma_{11}^2 - \Gamma_{13}^1 \Gamma_{11}^3 \\ &\quad - \Gamma_{10}^2 \Gamma_{21}^0 - \Gamma_{11}^2 \Gamma_{21}^1 - \Gamma_{12}^2 \Gamma_{21}^2 - \Gamma_{13}^2 \Gamma_{21}^3 \\ &\quad - \Gamma_{10}^3 \Gamma_{31}^0 - \Gamma_{11}^3 \Gamma_{31}^1 - \Gamma_{12}^3 \Gamma_{31}^2 - \Gamma_{13}^3 \Gamma_{31}^3 \\ &= 0 + \partial_1 \Gamma_{11}^1 + 0 + 0 \\ &\quad - \partial_1 \Gamma_{10}^0 - \partial_1 \Gamma_{11}^1 - \partial_1 \Gamma_{12}^2 - \partial_1 \Gamma_{13}^3 \\ &\quad + 0 + 0 + 0 + 0 \end{aligned}$$

$$\begin{aligned}
& +\Gamma_{11}^1\Gamma_{10}^0 + \Gamma_{11}^1\Gamma_{11}^1 + \Gamma_{11}^1\Gamma_{12}^2 + \Gamma_{11}^1\Gamma_{13}^3 \\
& \quad +0 + 0 + 0 + 0 \\
& \quad +0 + 0 + 0 + 0 \\
& \quad -\Gamma_{10}^0\Gamma_{01}^0 - 0 - 0 - 0 \\
& \quad -0 - \Gamma_{11}^1\Gamma_{11}^1 - 0 - 0 \\
& \quad -0 - 0 - \Gamma_{12}^2\Gamma_{21}^2 - 0 \\
& \quad -0 - 0 - 0 - \Gamma_{13}^3\Gamma_{31}^3 \\
= & \partial_1\Gamma_{11}^1 - \partial_1(\Gamma_{10}^0 + \Gamma_{11}^1 + \Gamma_{12}^2 + \Gamma_{13}^3) + \Gamma_{11}^1(\Gamma_{10}^0 + \Gamma_{11}^1 + \Gamma_{12}^2 + \Gamma_{13}^3) - (\Gamma_{10}^0\Gamma_{01}^0 \\
& \quad + \Gamma_{11}^1\Gamma_{11}^1 + \Gamma_{12}^2\Gamma_{21}^2 + \Gamma_{13}^3\Gamma_{31}^3) \\
= & \frac{\partial}{\partial r}\left(\frac{1}{2}\frac{\partial\lambda}{\partial r}\right) - \frac{\partial}{\partial r}\left(\frac{1}{2}\frac{\partial v}{\partial r} + \frac{1}{2}\frac{\partial\lambda}{\partial r} + \frac{2}{r}\right) + \frac{1}{2}\frac{\partial v}{\partial r}\left(\frac{1}{2}\frac{\partial v}{\partial r} + \frac{1}{2}\frac{\partial\lambda}{\partial r} + \frac{2}{r}\right) + \left(\frac{1}{2}\frac{\partial v}{\partial r}\right)^2 \\
& \quad + \left(\frac{1}{2}\frac{\partial\lambda}{\partial r}\right)^2 + \left(\frac{1}{r}\right)^2 + \left(\frac{1}{r}\right)^2 \\
= & \frac{1}{2}\lambda'' - \left(\frac{v''}{2} + \frac{\lambda''}{2} + \frac{2}{r^2}\right) + \left(\frac{v^2}{4} + \frac{v'\lambda'}{4} + \frac{v'}{r}\right) - \frac{v^2}{2} - \frac{2}{r^2} \\
& \quad = -\frac{v''}{2} - \frac{v'^2}{4} + \frac{v'\lambda'}{4} + \frac{v'}{r} \\
R_{11} = & -\frac{v''}{2} + \frac{\lambda'}{r} - \frac{v'\lambda'}{4} + \frac{v'^2}{4}.
\end{aligned}$$

7. Untuk  $R_{22}$

$$\begin{aligned}
R_{22} = & \partial_0\Gamma_{22}^0 + \partial_1\Gamma_{22}^1 + \partial_2\Gamma_{22}^2 + \partial_3\Gamma_{22}^3 \\
& -\partial_2\Gamma_{20}^0 - \partial_2\Gamma_{21}^1 - \partial_2\Gamma_{22}^2 - \partial_2\Gamma_{23}^3 \\
& +\Gamma_{22}^0\Gamma_{00}^0 + \Gamma_{22}^0\Gamma_{01}^1 + \Gamma_{22}^0\Gamma_{02}^2 + \Gamma_{22}^0\Gamma_{03}^3 \\
& +\Gamma_{22}^1\Gamma_{10}^0 + \Gamma_{22}^1\Gamma_{11}^1 + \Gamma_{22}^1\Gamma_{12}^2 + \Gamma_{22}^1\Gamma_{13}^3 \\
& +\Gamma_{22}^2\Gamma_{20}^0 + \Gamma_{22}^2\Gamma_{21}^1 + \Gamma_{22}^2\Gamma_{22}^2 + \Gamma_{22}^2\Gamma_{23}^3 \\
& +\Gamma_{22}^3\Gamma_{30}^0 + \Gamma_{22}^3\Gamma_{31}^1 + \Gamma_{22}^3\Gamma_{32}^2 + \Gamma_{22}^3\Gamma_{33}^3 \\
& -\Gamma_{20}^0\Gamma_{02}^0 - \Gamma_{21}^0\Gamma_{02}^1 - \Gamma_{22}^0\Gamma_{02}^2 - \Gamma_{23}^0\Gamma_{02}^3 \\
& -\Gamma_{20}^1\Gamma_{12}^0 - \Gamma_{21}^1\Gamma_{12}^1 - \Gamma_{22}^1\Gamma_{12}^2 - \Gamma_{23}^1\Gamma_{12}^3
\end{aligned}$$

$$\begin{aligned}
& -\Gamma_{20}^2 \Gamma_{22}^0 - \Gamma_{21}^2 \Gamma_{22}^1 - \Gamma_{22}^2 \Gamma_{22}^2 - \Gamma_{23}^2 \Gamma_{22}^3 \\
& -\Gamma_{20}^3 \Gamma_{32}^0 - \Gamma_{21}^3 \Gamma_{32}^1 - \Gamma_{22}^3 \Gamma_{32}^2 - \Gamma_{23}^3 \Gamma_{32}^3 \\
& = 0 + \partial_1 \Gamma_{22}^1 + 0 + 0 \\
& \quad -0 - 0 - 0 - \partial_2 \Gamma_{23}^3 \\
& \quad +0 + 0 + 0 + 0 \\
& +\Gamma_{22}^1 \Gamma_{10}^0 + \Gamma_{22}^1 \Gamma_{11}^1 + \Gamma_{22}^1 \Gamma_{12}^2 + \Gamma_{22}^1 \Gamma_{13}^3 \\
& \quad +0 + 0 + 0 + 0 \\
& \quad +0 + 0 + 0 + 0 \\
& \quad -0 - 0 - 0 - 0 \\
& \quad -0 - 0 - \Gamma_{22}^1 \Gamma_{12}^2 - 0 \\
& \quad -0 - \Gamma_{21}^2 \Gamma_{22}^1 - 0 - 0 \\
& \quad -0 - 0 - 0 - \Gamma_{23}^3 \Gamma_{32}^3 \\
& = \partial_1 \Gamma_{22}^1 - \partial_2 \Gamma_{23}^3 + \Gamma_{22}^1 (\Gamma_{10}^0 + \Gamma_{11}^1 + \Gamma_{12}^2 + \Gamma_{13}^3) - (\Gamma_{22}^1 \Gamma_{12}^2 + \Gamma_{21}^2 \Gamma_{22}^1 + \Gamma_{23}^3 \Gamma_{32}^3) \\
& = -\frac{\partial}{\partial r} (re^{-\lambda}) \frac{\partial \cos \theta}{\partial \theta \sin \theta} - re^{-\lambda} \left( \frac{1}{2} \frac{\partial v}{\partial r} + \frac{1}{2} \frac{\partial \lambda}{\partial r} + \frac{2}{r} \right) - 2 \left( -re^{-\lambda} \frac{1}{r} \right) - \cot^2 \theta \\
& = \left( -\frac{\partial e^{-\lambda}}{\partial r} r - e^{-\lambda} \frac{\partial r}{\partial r} \right) - \left( \frac{\sin \theta \frac{\partial(\cos \theta)}{\partial \theta} - \cos \theta \frac{\partial(\sin \theta)}{\partial \theta}}{\sin^2 \theta} \right) \\
& \quad - re^{-\lambda} \left( \frac{2}{r} + \frac{\lambda' + v'}{2} \right) + 2e^{-\lambda} - \frac{\cos^2 \theta}{\sin^2 \theta} \\
& = \frac{\partial \lambda}{\partial r} re^{-\lambda} - e^{-\lambda} + \frac{\sin \theta \sin \theta - \cos \theta \cos \theta}{\sin^2 \theta} - re^{-\lambda} \left( \frac{2}{r} + \frac{\lambda' + v'}{2} \right) + 2e^{-\lambda} - \frac{\cos^2 \theta}{\sin^2 \theta} \\
& = -e^{-\lambda} + \lambda' re^{-\lambda} + \frac{1}{\sin^2 \theta} - re^{-\lambda} \left( \frac{2}{r} + \frac{\lambda' + v'}{2} \right) + 2e^{-\lambda} - \frac{\cos^2 \theta}{\sin^2 \theta} \\
& = -e^{-\lambda} + r \left( \lambda' - \frac{2}{r} - \frac{\lambda' + v'}{2} + \frac{2}{r} \right) e^{-\lambda} + \left( \frac{1 - \cos^2 \theta}{\sin^2 \theta} \right) \\
& = -e^{-\lambda} + r \left( \frac{2\lambda' - \lambda' - v'}{2} \right) e^{-\lambda} + \frac{\sin^2 \theta}{\sin^2 \theta}
\end{aligned}$$

$$R_{22} = -e^{-\lambda} \left\{ \frac{r(v' - \lambda')}{2} + 1 \right\} + 1.$$

8. Untuk  $R_{33}$

$$\begin{aligned}
R_{33} &= \partial_0 \Gamma_{33}^0 + \partial_1 \Gamma_{33}^1 + \partial_2 \Gamma_{33}^2 + \partial_3 \Gamma_{33}^3 \\
&\quad - \partial_3 \Gamma_{30}^0 - \partial_3 \Gamma_{31}^1 - \partial_3 \Gamma_{32}^2 - \partial_3 \Gamma_{33}^3 \\
&\quad + \Gamma_{33}^0 \Gamma_{00}^0 + \Gamma_{33}^0 \Gamma_{01}^1 + \Gamma_{33}^0 \Gamma_{02}^2 + \Gamma_{33}^0 \Gamma_{03}^3 \\
&\quad + \Gamma_{33}^1 \Gamma_{10}^0 + \Gamma_{33}^1 \Gamma_{11}^1 + \Gamma_{33}^1 \Gamma_{12}^2 + \Gamma_{33}^1 \Gamma_{13}^3 \\
&\quad + \Gamma_{33}^2 \Gamma_{20}^0 + \Gamma_{33}^2 \Gamma_{21}^1 + \Gamma_{33}^2 \Gamma_{22}^2 + \Gamma_{33}^2 \Gamma_{23}^3 \\
&\quad + \Gamma_{33}^3 \Gamma_{30}^0 + \Gamma_{33}^3 \Gamma_{31}^1 + \Gamma_{33}^3 \Gamma_{32}^2 + \Gamma_{33}^3 \Gamma_{33}^3 \\
&\quad - \Gamma_{30}^0 \Gamma_{03}^0 - \Gamma_{31}^0 \Gamma_{03}^1 - \Gamma_{32}^0 \Gamma_{03}^2 - \Gamma_{33}^0 \Gamma_{03}^3 \\
&\quad - \Gamma_{30}^1 \Gamma_{13}^0 - \Gamma_{31}^1 \Gamma_{13}^1 - \Gamma_{32}^1 \Gamma_{13}^2 - \Gamma_{33}^1 \Gamma_{13}^3 \\
&\quad - \Gamma_{30}^2 \Gamma_{23}^0 - \Gamma_{31}^2 \Gamma_{23}^1 - \Gamma_{32}^2 \Gamma_{23}^2 - \Gamma_{33}^2 \Gamma_{23}^3 \\
&\quad - \Gamma_{30}^3 \Gamma_{33}^0 - \Gamma_{31}^3 \Gamma_{33}^1 - \Gamma_{32}^3 \Gamma_{33}^2 - \Gamma_{33}^3 \Gamma_{33}^3 \\
&\quad = 0 + \partial_1 \Gamma_{33}^1 + \partial_2 \Gamma_{33}^2 + 0 \\
&\quad \quad - 0 - 0 - 0 - 0 \\
&\quad \quad + 0 + 0 + 0 + 0 \\
&\quad + \Gamma_{33}^1 \Gamma_{10}^0 + \Gamma_{33}^1 \Gamma_{11}^1 + \Gamma_{33}^1 \Gamma_{12}^2 + \Gamma_{33}^1 \Gamma_{13}^3 \\
&\quad \quad + 0 + 0 + 0 + \Gamma_{33}^2 \Gamma_{23}^3 \\
&\quad \quad + 0 + 0 + 0 + 0 \\
&\quad \quad - 0 - 0 - 0 - 0 \\
&\quad \quad - 0 - 0 - 0 - \Gamma_{33}^1 \Gamma_{13}^3 \\
&\quad \quad - 0 - 0 - 0 - \Gamma_{33}^2 \Gamma_{23}^3 \\
&\quad \quad - 0 - \Gamma_{31}^3 \Gamma_{33}^1 - \Gamma_{32}^3 \Gamma_{33}^2 - 0 \\
&= (\partial_1 \Gamma_{33}^1 + \partial_2 \Gamma_{33}^2) + \Gamma_{33}^1 (\Gamma_{10}^0 + \Gamma_{11}^1 + \Gamma_{12}^2 + \Gamma_{13}^3) + \Gamma_{33}^2 \Gamma_{23}^3 - \Gamma_{33}^1 \Gamma_{13}^3 - \Gamma_{33}^2 \Gamma_{23}^3 \\
&\quad - (\Gamma_{31}^3 \Gamma_{33}^1 + \Gamma_{32}^3 \Gamma_{33}^2)
\end{aligned}$$

$$\begin{aligned}
&= \frac{\partial}{\partial r}(-r \sin^2 \theta e^{-\lambda}) + \frac{\partial}{\partial \theta}(-\sin \theta \cos \theta) - r \sin^2 \theta e^{-\lambda} \left( \frac{1}{2} \frac{\partial v}{\partial r} + \frac{1}{2} \frac{\partial \lambda}{\partial r} + \frac{2}{r} \right) \\
&\quad + \frac{2r \sin^2 \theta e^{-\lambda}}{r} + \sin \theta \cos \theta \cot \theta \\
&= \left( -\frac{\partial r}{\partial r} \sin^2 \theta e^{-\lambda} - \frac{\partial e^{-\lambda}}{\partial r} \right) + \left( \frac{\partial(-\sin \theta)}{\partial \theta} \cos \theta - \sin \theta \frac{\partial(\cos \theta)}{\partial \theta} \right) \\
&\quad - \sin^2 \theta e^{-\lambda} \left( r \frac{v' + \lambda'}{2} + 2 \right) + 2 \sin^2 \theta e^{-\lambda} + \frac{\sin \theta \cos \theta \cos \theta}{\sin \theta} \\
&= -\sin^2 \theta e^{-\lambda} + r \sin^2 \theta \lambda' e^{-\lambda} - \cos^2 \theta + \sin^2 \theta - \sin^2 \theta e^{-\lambda} \left( 2 + r \frac{v' + \lambda'}{2} - 2 \right) \\
&\quad + \cos^2 \theta \\
&= -\sin^2 \theta e^{-\lambda} \left( 1 - r \lambda' + \frac{v' + \lambda'}{2} \right) + \sin^2 \theta \\
&= -\sin^2 \theta e^{-\lambda} \left( 1 - \frac{2r \lambda'}{2} + \frac{r \lambda'}{2} + \frac{r v'}{2} \right) + \sin^2 \theta \\
R_{33} &= -\sin^2 \theta e^{-\lambda} \left\{ \frac{r}{2} (v' - \lambda') + 1 \right\} + \sin^2 \theta = \sin^2 \theta R_{22}.
\end{aligned}$$

Komponen Ricci di atas akan jadi tiga persamaan diferensial dengan suku eksponensial pada  $R_{00}e^{0-0} = 1$ . Sementara itu,  $R_{33}$  tidak diperlukan, karena hanya dibedakan oleh suku  $\sin^2 \theta$  dengan  $R_{22}$ . Ketiga persamaan tersebut adalah

$$\begin{aligned}
\frac{v''}{2} + \frac{v'}{r} - \frac{v' \lambda'}{4} + \frac{v'^2}{4} &= 0 \\
\frac{v''}{2} - \frac{\lambda'}{r} - \frac{v' \lambda'}{4} + \frac{v'^2}{4} &= 0 \\
e^{-\lambda} \left\{ \frac{r(v' - \lambda')}{2} + 1 \right\} - 1 &= 0.
\end{aligned}$$

(D.10)

Selisih dua persamaan pertama (2.105) memberikan



$$\frac{v' + \lambda'}{r} = 0 \tag{D.11}$$

atau

$$v' + \lambda' = 0 \tag{D.12}$$

sehingga

$$v' = -\lambda'. \tag{D.13}$$

Kita integralkan

$$\int \left( \frac{\partial v}{\partial r} + \frac{\partial \lambda}{\partial r} \right) dr = 0$$

$$v + \lambda = C_1. \tag{D.14}$$

Lalu

$$e^{-\lambda} \left\{ \frac{r(v' - \lambda')}{2} + 1 \right\} - 1 = 0$$

$$e^{-\lambda} \left\{ \frac{r(-\lambda' - \lambda')}{2} + 1 \right\} - 1 = 0$$

$$e^{-\lambda} \left\{ -\frac{r(2\lambda')}{2} + 1 \right\} - 1 = 0$$

$$e^{-\lambda} \{1 - r\lambda'\} = 1$$

$$\frac{\partial}{\partial r} \{r e^{-\lambda}\} = 1. \tag{D.15}$$

Kita integralkan

$$\begin{aligned} \int \frac{\partial}{\partial r} \{r e^{-\lambda}\} dr &= \int 1 dr \\ r e^{-\lambda} &= r + C_2 \\ e^{-\lambda} &= 1 + \frac{C_2}{r}. \end{aligned} \tag{D.16}$$

Untuk menentukan solusi konstanta integrasi  $C_1$ , kita berikan syarat batas ( $r \approx \infty$ ), sehingga elemen garis  $ds^2$  di atas haruslah mereduksi ke bentuk Minkowskian. Dengan kata lain

$$\begin{aligned} g_{00}(r \approx \infty) &= e^v = 1 \\ g_{11}(r \approx \infty) &= e^\lambda = -1 \end{aligned} \tag{D.17}$$

yang hanya dipenuhi bila  $v(r \approx \infty) = 0$  dan  $\lambda(r \approx \infty) = 0$ , karena  $e^\infty = e^0 = 1$ . Sehingga  $C_1 = 0$  dan

$$\begin{aligned} v + \lambda &= C_1 = 0 \\ v &= -\lambda. \end{aligned} \tag{D.18}$$

Untuk menentukan  $C_2$ , kita berikan apa yang disebut sebagai *limit medan lemah* (yaitu limit Newtonian dari TRU)

$$g_{00} \cong 1 + \frac{2}{c^2} \Phi \quad (\text{D.19})$$

di mana  $c$  adalah kecepatan cahaya dan  $\Phi = -\frac{GM}{r}$  adalah potensial gravitasi. Sementara itu kita tahu bahwa  $g_{00} = e^v$  dan  $v = -\lambda$ , sehingga

$$g_{00} \cong 1 + \frac{2}{c^2} \Phi = e^v = 1 + \frac{C_2}{r} \quad (\text{D.20})$$

atau

$$C_2 = -\frac{2r}{c^2} \frac{GM}{r} = -\frac{2GM}{c^2}. \quad (\text{D.21})$$

Akhirnya didapat

$$e^v = 1 + \frac{C_2}{r} = 1 + \frac{\left(-\frac{2GM}{c^2}\right)}{r} = 1 - \frac{2GM}{c^2 r} \quad (\text{D.22})$$

dan

$$e^{-\lambda} = 1 + \frac{C_2}{r} = 1 + \frac{\left(-\frac{2GM}{c^2}\right)}{r} = 1 - \frac{2GM}{c^2 r}$$

$$e^{\lambda} = \frac{1}{\left(1 - \frac{2GM}{c^2 r}\right)}.$$

(D.23)

Dengan demikian, *ruang-waktu Schwarzschild* kita dapatkan, yakni

$$ds^2 = \left(1 - \frac{2GM}{c^2 r}\right) dt^2 - \frac{dr^2}{\left(1 - \frac{2GM}{c^2 r}\right)} - r^2(d\theta^2 + \sin^2\theta d\phi^2).$$

(D.24)

Metrik ini menggambarkan medan gravitasi di luar objek simetri bola yang tidak bergantung pada distribusi materi di dalam objek (Hidayat, 2010; Purwanto, 2009).